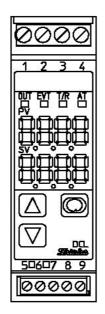
# DIN RAIL MOUNTED INDICATING CONTROLLER

### **INSTRUCTION MANUAL**





### Preface

Thank you for purchasing our DIN rail mounted indicating controller DCL-33A. This manual contains instructions for the mounting, functions, operations and notes when operating the DCL-33A. To ensure safe and correct use, thoroughly read and understand this manual before using this controller. To prevent accidents arising from the misuse of this controller, please ensure the operator receives this manual.

### Notes

- This instrument should be used in accordance with the specifications described in the manual.
- If it is not used according to the specifications, it may malfunction or cause a fire.
- Be sure to follow the warnings, cautions and notices. If they are not observed, serious injury or malfunction may occur.
- The contents of this instruction manual are subject to change without notice.
- Care has been taken to ensure that the contents of this instruction manual are correct, but if there are any doubts, mistakes or questions, please inform our sales department.
- This instrument is designed to be installed on a DIN rail within a control panel. If it is not, measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.
- Shinko Technos Co., Ltd. is not liable for any damage or secondary damage(s) incurred as a result of using this product, including any indirect damage.

### Safety Precautions (Be sure to read these precautions before using our products.)

The safety precautions are classified into categories: "Warning" and "Caution". Depending on circumstances, procedures indicated by  $\triangle$  Caution may result in serious consequences, so be sure to follow the directions for usage.



Procedures which may lead to dangerous conditions and cause death or serious injury, if not carried out properly.

Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.

### \land Warning

- To prevent an electric shock or fire, only Shinko or other qualified service personnel may handle the inner assembly.
- To prevent an electric shock, fire or damage to the instrument, parts replacement may only be undertaken by Shinko or other qualified service personnel.

### 

- To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
- This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.)
- External protection devices such as protection equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Also proper periodic maintenance is required.
- This instrument must be used under the conditions and environment described in this manual. Shinko Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

#### Caution with respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this instrument is not illegally exported.

### 1. Installation Precautions

### ▲ Caution

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category II, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to  $50^{\circ}$ C (32 to  $122^{\circ}$ F) that does not change rapidly, and no icing
- An ambient non-condensing humidity of 35 to 85 %RH
- No large capacity electromagnetic switches or cables through which large current is flowing.
- No water, oil or chemicals or where the vapors of these substances can come into direct contact with the unit
- Please note that the ambient temperature of this unit not the ambient temperature of the control panel must not exceed 50°C (122°F) if mounted within a control panel, otherwise the life of electronic components (especially electrolytic capacitors) may be shortened.

Note: Avoid setting this instrument directly on or near flammable material even though the case of this instrument is made of flame-resistant resin.

### 2. Wiring Precautions

### ▲ Caution

- Do not leave wire remnants in the instrument, because they could cause a fire or malfunction.
- Use correct fitting ferrules with an insulation sleeve for the terminal screw when wiring the DCL-33A.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- This instrument does not have a power switch, circuit breaker and fuse. Therefore it is necessary to install a power switch, circuit breaker and fuse externally near the controller.
- (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).

## 3. Operation and Maintenance Precautions

- It is recommended that auto-tuning be performed during the trial run.
- Do not touch live terminals. This may cause an electric shock or problems in operation.
- Turn the power supply to the instrument OFF before retightening the terminal or cleaning. Working on or touching the terminal with the power switched ON may result in severe injury or death due to electrical shock.
- Use a soft, dry cloth when cleaning the instrument. (Alcohol based substances may tarnish or deface the unit.)
- As the display section is vulnerable, be careful not to put pressure on, scratch or strike it with a hard object.

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Indication	-'		1	Ē	П	Ч	5	5	7	8	3	Ľ	F	
<b>Number,°</b> C/°F	-1	0	1	2	3	4	5	6	7	8	9	°C	°F	
Indication	Я	Π	Ь	Ē	ď	E	F	5	Н	1	L.	F	L	ā
Alphabet	A	4	В	С	D	Е	F	G	Н	-	J	К	L	Μ
Indication	Π	ø	Ρ	9	<i>_</i>	5	17	Ц	Н	Ū.	U I	Ч	111	
Alphabet	Ν	0	Р	Q	R	S	Т	U	V	W	Х	Υ	Ζ	

#### Characters used in this manual

### Contents

1.	Model	5
	1.1 Model	5
	1.2 How to Read the Model Label	5
2.	Name and Functions of Controller	6
3.	Mounting to the Control Panel	7
	3.1 Site Selection	7
	3.2 External Dimensions (Scale: mm)	7
	3.3 CT (Current transformer) External Dimensions (Scale: mm)	7
	3.4 Mounting to and Removal from the DIN Rail	8
4.	Wiring	9
	4.1 Terminal Arrangement	10
	4.2 Heater Burnout Alarm Output (W option)	10
5	Setup	11
0.	5.1 Main Setting Mode	12
	5.2 Sub Setting Mode	12
	5.3 Auxiliary Function Setting Mode 1	14
	5.4 Auxiliary Function Setting Mode 2	15
	5.5 Auxiliary Function Setting Mode 3	19
	5.6 Output MV (manipulated variable) Indication	26
6.	Simplified Converter Function	27
	6.1 Fine Adjustment of Converter Output (4 to 20 mA DC)	28
	6.2 Converter Setting Example	29
7.	Operation	30
0	Action Evaluations	24
8.	Action Explanations	31
	8.1 OUT1 Action	31
	8.2 OUT1 ON/OFF Control Action	31
	8.3 Heater Burnout Alarm Action	32
	8.4 Alarm Action	
	8.5 OUT2 (Heating/Cooling Control) Action	
	8.6 OUT2 (Heating/Cooling Control) Action (When Setting Overlap Band)	35
	8.7 OUT2 (Heating/Cooling Control) Action (When Setting Dead Band)	36
9.	AT (Auto-tuning)	37
10	Specifications	38
	10.1 Standard Specifications	38
	10.2 Optional Specifications	41
11	. Troubleshooting	44
	11.1 Indication	44
	11.2 Key Operation	45
	11.3 Control	46
12	Character Table	47
12	12.1 Main Setting Mode	47
	12.1 Main Setting Mode	47
	12.3 Auxiliary Function Setting Mode 1	47 48
	12.3 Auxiliary Function Setting Mode 1	40 49
	12.5 Auxiliary Function Setting Mode 3	49 51
Ke	ey Operation Flowchart	55

### 1. Model

#### 1.1 Model

DCL - 3	3	Α-	$\Box$		$\Box$ ,		Series name: DCL-300 (W22.5 x H75 x D100mm)	
Control action	3						PID	
Alarm		А					Selectable by keypad *1	
			R				Relay contact: 1a	
Control output O	רטכ	Г1	S				Non-contact voltage (for SSR drive): 12 V DC±15	
			Α				Direct current: 4 to 20 mA DC	
Input				Μ			Multi-range *2	
Supply voltage							100 to 240 V AC (standard)	
Supply voltage					1		24 V AC/DC *3	
						W (5A)	Heater burnout alarm output (5 A)	
						W (10A)	Heater burnout alarm output (10 A)	
				W (20A)	Heater burnout alarm output (20 A)			
Option	untion			W (50A)	Heater burnout alarm output (50 A)			
						DC	Heating/Cooling control output OUT2	
						C5	Serial communication EIA RS-485	
						EA	External setting input	
						EI	Set value memory external selection	

\*1: Alarm type (12 types and No alarm action) and status Energized/De-energized can be selected by keypad.

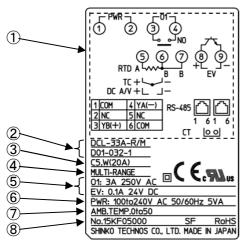
\*2: Thermocouple, RTD, Direct current and DC voltage can be selected by keypad.

\*3: Standard supply voltage is 100 to 240 V AC. Enter "1" after the input code only when ordering 24 V AC/DC.

#### 1.2 How to Read the Model Label

The model label is attached to the right side of the case.

(e.g.) DCL-33A-R/M, C5, W (20 A)

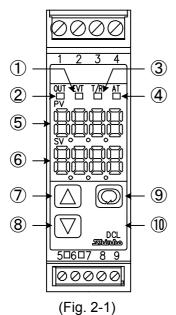


No.	Description	Example
1	Terminal arrangement	DCL-33A-R/M, C5, W(20A) (*1)
2	Model	DCL-33A-R/M, C5, W(20A)
3	Option	C5: Serial communication
		W(20A): Heater burnout alarm (20 A) (*2)
4	Input	MULTI-RANGE (Multi-range input)
5	Control output,	O1: 3 A 250 V AC (Control output OUT1)
	Event output	EV: 0.1 A 24 V DC (Event output EV)
6	Power supply,	100 to 240 V AC, 50/60 Hz
	Power consumption	5 VA
$\overline{\mathcal{O}}$	Recommended	0 to 50℃
	ambient temperature	
8	Serial number	No. 15KF05000

(\*1) Terminal arrangement differs depending on the model.

(\*2) For Heater burnout alarm output (W option), CT rated current is entered in bracket ( ).

### 2. Name and Functions of Controller



No.	Name	Description
1	EVT indicator	The red LED lights up when Event output [Alarm, Loop break alarm or Heater burnout alarm (W option)] is ON. The red LED also lights when control output OUT2 (DC option) is ON.
2	OUT indicator	The green LED lights up when control output OUT1 is ON. For direct current output, flashes in 125 ms cycles corresponding to the output MV.
3	T/R indicator	The yellow LED flashes during serial communication (C5 option) TX output (transmitting).
4	AT indicator	The yellow LED flashes while auto-tuning (AT) is performing.
5	PV Display	Indicates the PV (process variable), or setting characters in setting mode with a red LED.
6	SV Display	Indicates the SV (desired value), output MV (manipulated variable) or the set value in each setting mode with a green LED.
$\overline{\mathcal{O}}$	UP key	Increases the numeric value.
8	DOWN key	Decreases the numeric value.
9	MODE key	Switches the setting mode or registers the set data. (Registers the set data by pressing the MODE key.)
10	SUB-MODE key	<ul> <li>Enters Auxiliary function setting mode 2 in combination with the MODE key.</li> <li>If 'Control output OFF' is selected in [SUB-MODE key function]: Turns all outputs OFF as if the power were turned OFF.</li> <li>If 'Auto/Manual control' is selected in [SUB-MODE key function]: Switches Auto/Manual control.</li> <li>If 'Alarm HOLD cancel' is selected in [SUB-MODE key function]: Cancels Alarm HOLD.</li> </ul>

### 1 Caution

When setting the specifications and functions of this controller, connect mains power cable to terminals 1 and 2 first, then set them referring to "5. Setup" before performing "3. Mounting to the Control Panel" and "4. Wiring".

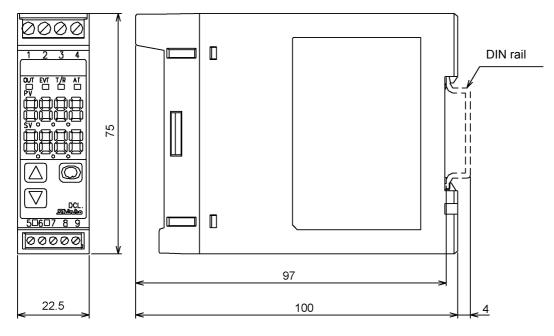
### 3. Mounting to the Control Panel

#### 3.1 Site Selection

### This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category II, Pollution degree 2

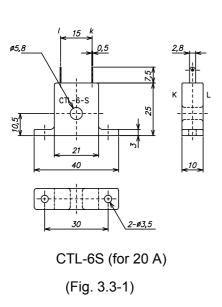
Ensure the mounting location corresponds to the following conditions:

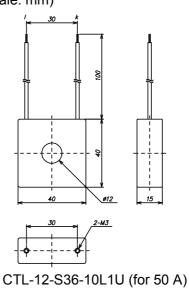
- A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- Few mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to 50  $^\circ C$  (32 to 122  $^\circ F)$  without rapid change, and no icing
- An ambient non-condensing humidity of 35 to 85 %RH
- No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil or chemicals or where the vapors of these substances can come into direct contact with the controller
- Please note that the ambient temperature of this unit not the ambient temperature of the control panel must not exceed 50°C (122°F) if mounted within a control panel, otherwise the life of the electronic components (especially electrolytic capacitors) may be shortened.
- 3.2 External Dimensions (Scale: mm)



(Fig. 3.2-1)

#### 3.3 CT (Current transformer) External Dimensions (Scale: mm)





(Fig. 3.3-2)

### 1 Caution

• Mount the DIN rail horizontally.

When the DIN rail is mounted vertically, be sure to use commercially available fastening plates at both ends of the DCL-33A series.

However, if the DIN rail is mounted horizontally in a position susceptible to vibration or shock, the fastening plates must be used as well.

• To remove this instrument, a flat blade screwdriver is required for pulling down the lever. Never turn the screwdriver when inserting it into the release lever. If excessive power is applied to the lever, it may break.

#### • Recommended fastening plate

Manufacturer	N	lodel
Omron Corporation	End plate	PFP-M
IDEC Corporation	Fastening plate	BNL6
Panasonic Electric Works Co., Ltd.	Fastening plate	ATA4806

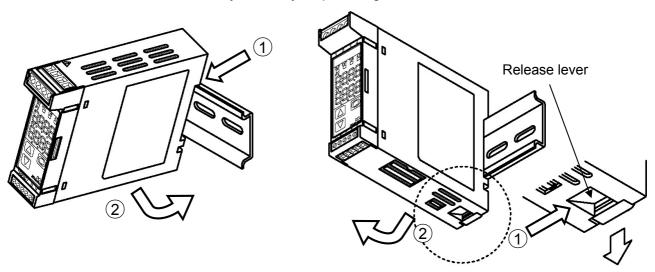
#### Mounting to the DIN rail (Fig. 3.4-1)

First, hook 1 of the DCL-33A on the upper side of the DIN rail.

**Second**, making ① part of the DCL-33A as a support, fit the lower part ② of the DCL-33A to the DIN rail. DCL-33A will be completely fixed to DIN rail with a "Click" sound.

#### Removal from the DIN rail (Fig. 3.4-2)

- ① Insert a flat blade screwdriver into the release lever, and pull it down.
- <sup>(2)</sup> The lock to the DIN rail will be released, then remove the unit from the DIN rail. Be sure to hold onto the unit firmly, or it may drop to the ground.



(Fig. 3.4-1) Mounting

(Fig. 3.4-2) Removal

### 4. Wiring

### ᡗ Warning

Turn the power supply to the instrument OFF before wiring or checking. Working on or touching the terminal with the power switched ON may result in severe injury

or death due to electrical shock.

### ▲ Caution

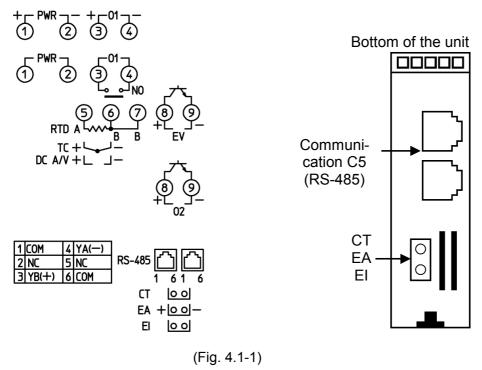
- Do not leave wire remnants in the DCL-33A when wiring, because they could cause a fire or malfunction.
- Insert the connecting cable into the designated connector securely. Not doing so could cause malfunction due to imperfect contact.
- Connect the AC power to the designated terminal as is written in this instruction manual. Otherwise it may burn and damage the DCL-33A.
- Tighten the terminal screw using the specified torque. Excessive force could damage the terminal screw and deface the case.
- Use a thermocouple and compensating lead wire that corresponds to the sensor input specification of this unit.
- Use the 3-wire RTD that corresponds to the sensor input specification of this unit.
- When using DC voltage and current inputs, be careful not to confuse polarity when wiring.
- For a 24 V DC power source, ensure polarity is correct.
- Keep input wires (Thermocouple, RTD, etc.) away from power source and load wires when wiring.
- Do not apply a commercial power source to the sensor connected to the input terminal nor allow the power source to come into contact with the sensor.
- To prevent the unit from harmful effects of unexpected level noise, it is recommended that a surge absorber be installed between the electromagnetic switch coils.
- This unit does not have a built-in power switch, circuit breaker and fuse. Therefore it is necessary to install a power switch, circuit breaker and fuse externally near the controller.

(Recommended fuse: Time-lag fuse, Rated voltage 250 V AC, Rated current 2 A)

When using ferrules, use the following ferrules and crimping pliers made by Phoenix Contact GMBH & CO. • Recommended ferrules and tightening torgue

Terminal number	Terminal screw	Ferrules with insulation sleeve	Conductor cross sections	Tightening torque	Crimping pliers
1 to 4	M2.6	AI 0.25-8 YE	0.2 to 0.25 mm <sup>2</sup>	0.5 to 0.6 N•m	CRIMPFOX ZA3
		AI 0.34-8 TQ	0.25 to 0.34 mm <sup>2</sup>		CRIMPFOX UD6
		AI 0.5-8 WH	0.34 to 0.5 mm <sup>2</sup>		
		AI 0.75-8 GY	0.5 to 0.75 mm <sup>2</sup>		
		AI 1.0-8 RD	0.75 to 1.0 mm <sup>2</sup>		
		AI 1.5-8 BK	1.0 to 1.5 mm <sup>2</sup>		
5 to 9	M2.0	AI 0.25-8 YE	0.2 to 0.25 mm <sup>2</sup>	0.22 to 0.25 N•m	
		AI 0.34-8 TQ	0.25 to 0.34 mm <sup>2</sup>	]	
		AI 0.5-8 WH	0.34 to 0.5 mm <sup>2</sup>		

#### 4.1 Terminal Arrangement



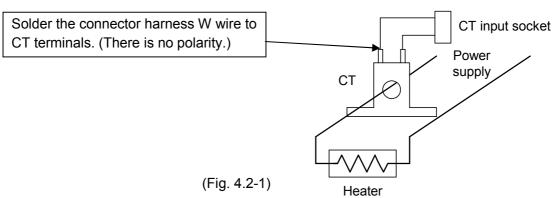
Name	Description
PWR	Power supply: 100 to 240 V AC or 24 V AC/DC
	For 24 V DC, ensure polarity is correct.
01	Control output OUT1
тс	Thermocouple input
RTD	Resistance temperature detector input
DC	Direct current input, DC voltage input (*1)
EV	Event output
	Outputs when Alarm, Loop break alarm or Heater burnout alarm output (W option) is ON.
02	Control output OUT2 [Heating/Cooling control output (DC option)]
RS-485	Serial communication (C5 option)
СТ	Current transformer input [Heater burnout alarm output (W option)]
EA	External setting input (EA option)
EI	Event input DI [Set value memory external selection (EI option)]

(\*1) If direct current input (Externally mounted 50  $\Omega$  shunt resistor) is designated, connect a 50  $\Omega$  shunt resistor (sold separately) between input terminals.

#### 4.2 Heater Burnout Alarm Output (W option)

#### This alarm is not available for detecting current under phase control.

Use the current transformer (CT) provided, and pass one lead wire of the heater circuit into the hole of the CT. When wiring, keep the CT wire away from any AC source or load wires to avoid the external interference.



### 5. Setup

Connect mains power cable to terminals 1 and 2, and turn the power ON.

The PV Display indicates sensor input characters and temperature unit, and the SV Display indicates the input range high limit value for approx. 3 seconds. (Table 5-1)

(If any other value is set in [Scaling high limit], the SV Display indicates the value.)

During this time all outputs and the LED indicators are in OFF status.

After that, the control starts, indicating PV (process variable) on the PV Display, and SV (desired value) on the SV Display.

(Table 5-1)						
Input Type	Input F	Range	Resolution			
к	–200 to 1370 ℃	–320 to 2500 °F	1℃ (°F)			
n.	–199.9 to 400.0℃	–199.9 to 750.0°F	0.1℃ (°F)			
J	–200 to1000 °C	<b>–320 to1800</b> °F	1℃ (°F)			
R	0 to 1760 ℃	0 to 3200 °F	1℃ (°F)			
S	0 to 1760 ℃	0 to 3200 °F	1℃ (°F)			
В	0 to 1820 ℃	0 to 3300 °F	1℃ (°F)			
E	–200 to 800 °C	–320 to 1500 °F	1℃ (°F)			
Т	–199.9 to 400.0℃	–199.9 to 750.0°F	0.1℃ (°F)			
N	–200 to 1300 ℃	–320 to 2300 °F	1℃ (°F)			
PL-Ⅱ	0 to 1390 ℃	0 to 2500 °F	1℃ (°F)			
C (W/Re5-26)	0 to 2315 ℃	0 to 4200 °F	1℃ (°F)			
Pt100	–199.9 to 850.0 °C	–199.9 to 999.9°F	0.1℃ (°F)			
FILO	–200 to 850 °℃	–300 to 1500 °F	1℃ (°F)			
JPt100	–199.9 to 500.0 °C	–199.9 to 900.0°F	0.1℃ (°F)			
JFIIOU	<b>–200 to 500</b> ℃	<b>–300 to 900</b> °F	1℃ (°F)			
4 to 20 mA DC	–1999 to	o 9999 (*1), (*2)	1			
0 to 20 mA DC	–1999 to	o 9999 (*1), (*2)	1			
0 to 1 V DC	–1999 to	1				
0 to 5 V DC	-1999 to	1				
1 to 5 V DC	–1999 te	1				
0 to 10 V DC	–1999 to	1				
4 to 20 mA DC		o 9999 (*1), (*3)	1			
0 to 20 mA DC		o 9999 (*1), (*3)	1			

#### (Table 5-1)

(\*1) Input range and decimal point place can be changed.

(\*2) Connect a 50  $\,\Omega\,$  shunt resistor (sold separately) between input terminals.

(\*3) This input type has a built-in shunt resistor (50  $\Omega$ ).

#### 5.1 Main Setting Mode

Character	Setting Item, Description, Setting Range	Factory Default
5	SV1	0°C
• • • • • • • • • • • • • • • • • • • •	<ul> <li>Sets the SV1 (desired value) for control target.</li> <li>Setting range: Scaling low limit to scaling high limit (For DC volta placement of the decimal point follows the selection.)</li> </ul>	ge, current input, the

#### 5.2 Sub Setting Mode

Character	Setting Item, Description, Setting Rang	е	Factory Default				
85	AT Perform/Cancel		AT Cancel				
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	<ul> <li>Selects AT (auto-tuning) Perform/Cancel.</li> </ul>						
	AT will be forced to stop if it has not been completed within 4 hours.						
	• AT will stop in the following cases.						
	- Direct/Reverse action in Event input DI is changed	l.					
	- Control ON/OFF in Event input DI is changed.						
	- Preset output 2 in Event input DI is turned ON.						
	<ul> <li>Auto/Manual control in Event input DI is changed.</li> <li>'Integral action Holding (Stop)' is selected in Event</li> </ul>						
	- For DC input and direct current output: When 'Out		lected in [Output				
	status when input errors occur], and if input errors						
	•: AT Cancel, AT Perform	000011					
P	OUT1 proportional band		2.5%				
/	Sets OUT1 proportional band.						
	ON/OFF control when set to 0.0.						
	Setting range: 0.0 to 110.0%						
Р_Ь	OUT2 proportional band		1.0 times				
·	Sets OUT2 proportional band.						
	OUT2 proportional band: Multiplied value of OUT1	proportional I	band.				
	ON/OFF control when set to 0.0. • Available only when Heating/Cooling control output	(DC option)	is ordered				
	Not available if OUT1 is in ON/OFF control		is olucieu.				
	• Setting range: 0.0 to 10.0 times						
/	Integral time		200 sec				
/ []	Sets the integral time.						
	Setting the value to 0 disables this function.						
	<ul> <li>Not available if OUT1 is in ON/OFF control.</li> </ul>						
	Setting range: 0 to 3600 seconds						
d	Derivative time		50 sec				
	Sets the derivative time.						
	• Setting the value to 0 disables this function.						
	• Not available if OUT1 is in ON/OFF control.						
	Setting range: 0 to 1800 seconds		<b>F00</b> /				
7	ARW (Anti-reset windup)		50%				
	<ul> <li>Sets anti-reset windup.</li> <li>Available only for PID control.</li> </ul>						
	Setting range: 0 to 100%						
(	OUT1 proportional cycle	Relay cont	act output: 30 sec				
<b>c</b>	Sets the OUT1 proportional cycle.	-	ct voltage output: 3 sec				
	Not available if OUT1 is in ON/OFF control.						
	Not available for direct current output.						
	Setting range: 1 to 120 seconds						
, (****)	OUT2 proportional cycle		3 sec				
c_b	• Sets the OUT2 proportional cycle.		0.960				
	<ul> <li>Available only when Heating/Cooling control output</li> </ul>	(DC option)	is ordered				
	Not available if OUT2 is in ON/OFF control.						
	Setting range: 1 to 120 seconds						
	• Setting range. 1 to 120 seconds		0.0				
- 4EF			0.0				
	Sets the reset value manually.     Available only for P or PD control						
	Available only for P or PD control.     Softing range: + Propertional band converted value		tago ourront input the				
	Setting range: ±Proportional band converted value						
	placement of the decimal point follow	ws the select	юп.)				

Character	Setting Item, Description, Setting Range	Factory Default							
R (	Alarm 1 value	<b>0</b> ℃							
/ / /	Sets Alarm 1 action point.								
	• Alarm 1 value matches Alarm 1 low limit alarm value in the follow	ing cases:							
		Vhen 'High/Low limits independent alarm', 'High/Low limit range independent alarm'							
	or 'High/Low limits with standby independent alarm' is selected in								
	When Alarm, Loop break alarm and Heater burnout alarm (W opt	ion) are used							
	together, they utilize common output terminals.								
	• Not available if No alarm action is selected in [Alarm 1 type].								
	• Setting range: See (Table 5.2-1). (For DC voltage, current input, t	the placement of the							
	decimal point follows the selection.)								
Here and	Heater burnout alarm value	0.0 A							
XX.X	• Sets the heater current value for Heater burnout alarm.								
alternating	• Setting the value to 0.0 disables Heater burnout alarm action.								
display	Upon returning to set limits, the alarm will stop.								
	When Heater burnout alarm, Alarm and Loop break alarm are us	ed together, they							
	utilize common output terminals. • Available only when Heater burnout alarm (W option) is ordered.								
	Rated current 5 A: 0.0 to 5.0 A								
	Rated current 10A: 0.0 to 10.0 A								
	Rated current 20A: 0.0 to 20.0 A								
	Rated current 50A: 0.0 to 50.0 A								
LP_F	Loop break alarm time	0 minutes							
·_ · _ ·	<ul> <li>Sets the time to assess the Loop break alarm. (See "Loop break alarn</li> </ul>								
	<ul> <li>Setting the value to 0 disables Loop break alarm.</li> </ul>	- 1 /							
	• When Loop break alarm, Alarm and Heater burnout alarm are use	d together, they							
	utilize common output terminals.								
	Setting range: 0 to 200 minutes								
LP_H	Loop break alarm span	0°C							
_	• Sets the span to assess the Loop break alarm. (See "Loop break alar	rm" on p.18.)							
	Setting the value to 0 disables Loop break alarm.								
	• When Loop break alarm, Alarm and Heater burnout alarm are used together, they								
	utilize common output terminals.								
	• Setting range: Thermocouple, RTD input: 0 to 150℃ (°F) or 0.0 to	. ,							
	DC voltage, current input: 0 to 1500 (The placement of the decimation)	al point follows the							
	selection.)								

#### (Table 5.2-1)

Alarm type	Setting range	
High limit alarm	–(Scaling span) to scaling span	Minimum
Low limit alarm	–(Scaling span) to scaling span	negative value:
High/Low limits alarm	0 to scaling span	-199.9 or -1999
High/Low limit range alarm	0 to scaling span	
Process high alarm	Scaling low limit value to scaling high limit value	Maximum
Process low alarm	Scaling low limit value to scaling high limit value	positive value:
High limit with standby alarm	–(Scaling span) to scaling span	999.9 or 9999
Low limit with standby alarm	–(Scaling span) to scaling span	
High/Low limits with standby alarm	0 to scaling span	
High/Low limits independent alarm	0 to scaling span	
High/Low limit range	0 to scaling span	
independent alarm		
High/Low limits with standby	0 to scaling span	
independent alarm		

#### 5.3 Auxiliary Function Setting Mode 1

Character	Setting Item, Description, Setting Range	Factory Default
Lock	Set value lock	Unlock
	<ul> <li>Locks the set values to prevent setting errors. The setting item to be locked depends on the selection.</li> <li>Auto-tuning (AT) cannot be carried out if Lock 1 or Lock 2 is selection.</li> <li>Auto-tuning (AT) cannot be carried out if Lock 1 or Lock 2 is selection.</li> <li>I contend to the set values can be changed.</li> <li>I contend to the set values can be changed.</li> <li>I contend to the set values of the set values can be changed.</li> <li>I contend to the set values of the set values can be changed.</li> <li>I contend to the set values of the s</li></ul>	er/Converter – can be heir previous values
	Do not change any setting item in Auxiliary fun If any item in Auxiliary function setting mode 2 affect other setting items such as the SV and A Be sure to select Lock 3 when changing the se software communication. (If a value set by the communication is the same as the value before value will not be written in non-volatile memory	is changed, it will Narm value. It value frequently via software the setting, the
4o	<ul><li>Sensor correction</li><li>Sets the sensor correction value. (For details, see 'Sensor correction's set is a set in the sensor correction will be set in the sensor</li></ul>	0.0°C
	<ul> <li>Setting range: Thermocouple, RTD input: -100.0 to 100.0℃ (°F) DC voltage, current input: -1000 to 1000 (The place point follows the selection.)</li> </ul>	ement of the decimal
cāhl	Communication protocol	Shinko protocol
	<ul> <li>Available only when serial communication (C5 option) is ordered.</li> <li>         ・</li></ul>	
	Instrument number	0
<i>c</i> nna	<ul> <li>Sets an individual instrument number for each DCL-33A when conduct DCL-33A units in serial communication.</li> <li>Available only when serial communication (C5 option) is ordered.</li> <li>Setting range: 0 to 95</li> </ul>	nnecting multiple
cā5P	Communication speed	9600 bps
	<ul> <li>Selects the speed in accordance with the host computer.</li> <li>Available only when serial communication (C5 option) is ordered.</li> <li>24: 2400 bps</li> <li>48: 4800 bps</li> <li>56: 9600 bps</li> <li>192: 19200 bps</li> <li>384: 38400 bps</li> </ul>	
cāPr	Parity	Even
_	<ul> <li>Selects the parity.</li> <li>Available only when serial communication (C5 option) is ordered. Not available if Shinko protocol is selected in [Communication pro</li> <li>ロロロモ: No parity とどとの: Even ロロロビ: Odd</li> </ul>	
<u>ะกั</u> รโ	Stop bit	1
	<ul> <li>Selects the stop bit.</li> <li>Available only when serial communication (C5 option) is ordered. Not available if Shinko protocol is selected in [Communication pro-</li> <li>Selection: 1 or 2</li> </ul>	otocol].

#### 5.4 Auxiliary Function Setting Mode 2

Character	Setting Item, Description, Setting Range	Factory Default			
4E24	Input type	K (–200 to 1370°℃)			
	<ul> <li>Selects a sensor type and temperature unit from thermocouple (10 types),</li> </ul>				
	RTD (2 types), Direct current (4 types) and DC voltage (4 types) and °C/°F.				
	When changing input from DC voltage to other inputs, of				
	connected to this controller, then change the input. The input circuit may break				
	if the input is changed with the sensor connected.				
	<i>E K</i> −200 to 1370°C <i>E F K</i>	–320 to 2500°F			
	<u>⊢</u> <u>−</u> 199.9 to 400.0°C <u>⊢</u> <u></u> .	–199.9 to 750.0°F			
	J	–320 to 1800°F			
	$r \square E R = 0$ to $1760^{\circ}C r \square F R$	0 to 3200°F			
	Υ□Γ         S         0 to         1760℃         Υ□Γ         S	0 to 3200°F			
	$b \subseteq C$ B 0 to 1820°C $b \subseteq F$ B	0 to 3300°F			
	$E \square E = -200$ to $800^{\circ}C$ $E \square F$ E	–320 to 1500°F			
	<i>Г</i>	–199.9 to 750.0°F			
	¬□ N −200 to 1300°C ¬□F N	–320 to 2300°F			
	<i>PL_2E</i> PL-II 0 to 1390℃ <i>PL_2F</i> PL-II	0 to 2500°F			
	$\Box \Box \Box \Box = \Box \Box = \Box = \Box = \Box = \Box = \Box = \Box =$	-			
	<i>₽Г. [</i> Pt100 −199.9 to 850.0°C <i>РГ. F</i> Pt100	–199.9 to 999.9°F			
	<i>JP</i> , <i>I</i> , JPt100 −199.9 to 500.0°C				
	Pr⊡r Pt100 –200 to 850℃ Pr⊡r Pt100	–300 to 1500°F			
	<u>/₽/ [</u> JPt100 –200 to 500℃ <u></u> /₽/ F JPt100	<b>–300 to 900</b> °F			
	<i>닉己囗吊</i>   4 to 20 mA −1999 to 9999 (Externally mounted 5	50 Ω shunt resistor)			
	$ \Box Z \Box B $ 0 to 20 mA $-1999$ to 9999 (Externally mounted 5	50 Ω shunt resistor)			
	□□ 1 U 0 to 1 V -1999 to 9999				
	□□5 <i>H</i> 0 to 5 V –1999 to 9999				
	/□5월   1 to 5 V –1999 to 9999				
	□ I□ H 0 to 10 V -1999 to 9999				
	∀ਟੇΩi   4 to 20 mA –1999 to 9999 (Built-in 50 Ω shunt ι	resistor)			
	$\square \square \square \square \square$ 0 to 20 mA $-1999$ to 9999 (Built-in 50 $\Omega$ shunt i	resistor)			
$5\Gamma LH$	Scaling high limit	<b>1370</b> ℃			
	<ul> <li>Sets the scaling high limit value.</li> </ul>				
	Setting range: Scaling low limit to input range high limit				
	(For DC voltage, current input, the placement of the decimal	point follows the selection.)			
4 <i>5</i> 6 6	Scaling low limit	<b>−200</b> °C			
	<ul> <li>Sets the scaling low limit value.</li> </ul>				
	Setting range: Input range low limit to scaling high limit				
	(For DC voltage, current input, the placement of the decimal	point follows the selection.)			
dP	Decimal point place	No decimal point			
	<ul> <li>Selects the decimal point place.</li> </ul>				
	Not available if thermocouple or RTD is selected in [input ty	pe].			
	• $\Box \Box \Box \Box$ : No decimal point				
	$\Box \Box \Box \Box \Box \Box$ : 1 digit after decimal point				
	$\Box \Box \Box \Box \Box$ : 2 digits after decimal point				
	$\Box \Box \Box \Box \Box$ : 3 digits after decimal point				
FILF	PV filter time constant	0.0 sec			
·	Sets the PV filter time constant.				
	If the set value is too large, it affects control results due to the	ne response delay.			
	Setting range: 0.0 to 10.0 seconds	· •			
oLH	OUT1 high limit	100%			
	Sets the OUT1 high limit value.				
	Available for direct current output. Not available if OUT1 is i	n ON/OFF control.			
	Setting range: OUT1 low limit value to 100%				
	(Direct current output type: OUT1 low limit va	lue to 105%)			

Character	Setting Item, Description, Setting Range	Factory Default
oLL	OUT1 low limit	0%
	Sets the OUT1 low limit value.	
	<ul> <li>Available for direct current output. Not available if OUT1 is in ON</li> </ul>	VOFF control.
	<ul> <li>Setting range: 0% to OUT1 high limit value</li> </ul>	
	(Direct current output type: –5% to OUT1 high lim	
H $H$ $H$ $H$ $H$ $H$ $H$ $H$ $H$ $H$	OUT1 ON/OFF hysteresis	1.0℃
	<ul> <li>Sets the ON/OFF hysteresis for the OUT1.</li> </ul>	
	<ul> <li>Available only for ON/OFF control (P=0).</li> </ul>	
	• Setting range: Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decin	nal point follows the
	selection.)	
cRcF	OUT2 cooling mode	Air cooling
	• Selects air, oil or water cooling for OUT2 action.	
	Available only when Heating/Cooling control (DC option) is order	red.
	Not available if OUT2 is in ON/OFF control action	
	교위/: Water cooling	
ol Hb	OUT2 high limit	100%
	• Sets OUT2 high limit value.	
	Available only when Heating/Cooling control (DC option) is order	red.
	Not available if OUT2 is in ON/OFF control action	
	Setting range: OUT2 low limit value to 100%     OUT2 low limit	00/
ollb		0%
	• Sets OUT2 low limit value.	rod
	<ul> <li>Available only when Heating/Cooling control (DC option) is orde Not available if OUT2 is in ON/OFF control action</li> </ul>	red.
	Setting range: 0% to OUT2 high limit value	
db	Overlap/Dead band	0.0°C
	•	0.00
	<ul> <li>Sets Overlap/Dead band.</li> <li>Available only when Heating/Cooling control (DC option) is orde</li> </ul>	rod
	Not available if OUT2 is in ON/OFF control action	ieu.
	Setting range:	
	Thermocouple, RTD input: –100.0 to 100.0°C (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decin	nal point follows the
	selection.)	
<i>Н</i> УЧЬ	OUT2 ON/OFF hysteresis	1.0℃
	Sets the ON/OFF action hysteresis for the OUT2.	
	• Available only when Heating/Cooling control (DC option) is orde	red.
	Available only when OUT2 is in ON/OFF control action (P=0).	
	• Setting range: Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placeme	
	point follows the select	,
RL IF	Alarm 1 type	No alarm action
	Selects an Alarm 1 type.	
	Note: If Alarm 1 type is changed, Alarm 1 value returns to 0 (	).0).
	• : No alarm action	
	High limit alarm	
	Low limit alarm	
	High/Low limits alarm	
	ú du High/Low limit range alarm	
	유는:: Process high alarm	
	ר אין אין די Process low alarm	
	$H \square \tilde{\omega}$ : High limit with standby alarm	
	$L = \tilde{\mu}$ : Low limit with standby alarm	
	$H = \Box \tilde{\mu}$ : High/Low limits with standby alarm	
	/ HL .: High/Low limits independent alarm	
	$i  \vec{\omega} i  \vec{\omega}$ : High/Low limit range independent alarm	
	$H_{L}$ , $\bar{\mu}$ : High/Low limits with standby independent alarm	

Character	Setting Item, Description, Setting Range	Factory Default
RILĀ	Alarm 1 Energized/De-energized	Energized
	• Selects Alarm 1 action Energized/De-energized. (For details, see p.	
	Not available if No alarm action is selected in [Alarm 1 type].	
	• ngnL : Energized	
	- Ε Β'->: De-energized	
R IHJ	Alarm 1 HOLD function	Not holding
	• Selects either Holding or Not holding in Alarm 1.	
	If "Holding" is set, once alarm is activated, the alarm output remain	S ON
	until the power is turned off. • Not available if No alarm action is selected in [Alarm 1 type].	
	• The available in the alarm action is selected in [Alarm 1 type].	
	Hok d: Holding	
	Alarm 1 hysteresis	1.0℃
8 IHY	Sets Alarm 1 hysteresis.	1.0 0
	• Not available if No alarm action is selected in [Alarm 1 type].	
	Setting range:	
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	point follows the
	selection.)	
R ដេម	Alarm 1 delay time	0 sec
	Sets Alarm 1 action delay time.	
	When the setting time has elapsed after the input enters the alarm	output range, the
	alarm is activated.	
	• Not available if No alarm action is selected in [Alarm 1 type].	
	Setting range: 0 to 9999 seconds	<b>.</b>
conľ	Direct/Reverse action	Reverse (Heating)
	<ul> <li>Selects either Reverse (Heating) or Direct (Cooling) control action.</li> </ul>	action
	・ <i>HE 吊L</i> : Reverse (Heating) action	
	c = a = L: Direct (Cooling) action	
י דודו	AT bias	<b>20</b> ℃
85_6	Set the AT (auto-tuning) bias value.	
	• Not available if DC voltage or current input is selected in [Input type	e].
	Available only for PID control action	-
	• Setting range: 0 to 50°℃ (0 to 100°F) or 0.0 to 50.0℃ (0.0 to 100.0°F	7)
48_6	SVTC bias	0
	• Control desired value adds SVTC bias value to the value received	by the SVTC
	command.	
	• Available only when serial communication (C5 option) is ordered.	
	• Setting range: ±20% of the scaling span	
EoUF	Output status when input errors occur	Output OFF
	• Selects the output status of OUT1 when DC input is in overscale of	r underscale.
	(See "Output status when input errors occur" on p.18.)	
	• Available only for DC input and direct current output.	
	<ul> <li> <i>p F F</i></li></ul>	(20  mA) or between
	OUT1 low limit value and OUT1 high limit value, dep	· /
	Controller/Converter	Controller
FUnc	Selects either controller or converter function.	
	(See "6. Simplified Converter Function" on pages 27 – 29.)	
	Available only for direct current output type.	
	• こっぽっ: Controller, こっぱぽ: Converter	

#### **Sensor correction function**

This corrects the input value from the sensor. When a sensor cannot be set at the exact location where control is desired, the sensor-measured temperature may deviate from the temperature in the controlled location.

When using multiple controllers, sometimes the measured temperatures (input value) do not match (even if SV is the same value) due to differences in sensor accuracy or dispersion of load capacities. In such a case, the control can be set at the desired temperature by adjusting the input value of sensors. However, it is effective within the input rated range regardless of the sensor correction value. PV after sensor correction = Current PV + (Sensor correction value)

#### Loop break alarm

The alarm will be activated if the PV (process variable) does not **reach** the Loop break alarm span setting within the time allotted to assess the Loop break alarm after the MV (manipulated variable) has reached 100% or the control output high limit value. The alarm will also be activated if the PV (process variable) does not **drop to** the Loop break alarm span setting within the time allotted to assess the Loop break alarm after the MV has reached 0% or the control output low limit value.

When the control action is Direct (Cooling), read "drop to" for "reach" and vice versa.

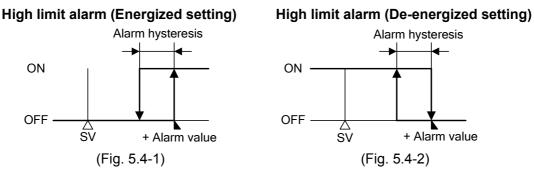
#### **Energized/De-energized**

#### [If alarm action Energized is selected]

When the alarm output indicator is lit, the alarm output (between terminals 8 and 9) is conducted (ON). When the alarm output indicator is unlit, the alarm output is not conducted (OFF).

#### [If alarm action De-energized is selected]

When the alarm output indicator is lit, the alarm output (between terminals 8 and 9) is not conducted (OFF). When the alarm output indicator is unlit, the alarm output is conducted (ON).



#### Output status when input errors occur

Control output status differs depending on the selection in [Output status when input errors occur] as follows.

			C	Dutput sta	tus		
Output status	Contents	Controller/Converter					
when input	and		Controller			Converter	
errors occur	Indication	OUT1 OUT2 OUT1		JT1			
(*1)		Direct action	Reverse action	Direct	Reverse	Direct	Reverse
0700 0FF0	"" flashes.	ON (20 mA) or OUT1 high limit value (*2) OFF (4 mA) or OUT1 low limit value	OFF (4 mA) or OUT1 low limit value	OUT2 low limit	t value	20 mA or OUT1 high limit value	4 mA or OUT1 low limit value
on	"" flashes.	OFF (4 mA) or	ON (20 mA) or OUT1 high limit value (*2)	OUT2		4 mA or OUT1	20 mA or OUT1
oFF		OUT1 low limit value	OFF (4 mA) or OUT1 low limit value	low limit value		low limit value	high limit value

(\*1) [Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

If OUT1 is not Direct current output, the output status will be the same as when  $\Box F F \square$  is selected in [Output status when input errors occur].

For manual control, the preset MV is output.

(\*2) Outputs a value between OFF (4 mA) and ON (20 mA) or between OUT1 low limit value and OUT1 high limit value, depending on deviation.

#### 5.5 Auxiliary Function Setting Mode 3

Character		Setting Item, Descripti	on, Setting Ran	ge	Factory Default	
El n	Event in	put DI allocation			No event	
	Selects Event input DI function from the following.					
	<ul> <li>Availab</li> </ul>	le only when Set value merr	ory external sele	ection (EI option)	is selected.	
		Event Input Function	Input ON	Input OFF	Remarks	
		Event input Function	(Closed)	(Open)	Remarks	
		No event				
	<u>00</u> 1	Set value memory	SV2	SV1	SV1/SV2 selectable	
	002	Control ON/OFF (*1)	Control OFF	Control ON	Control ON/OFF selectable	
	003	Direct/Reverse action	Direct	Reverse	Direct/Reverse control selectable	
	004	Preset output 1 ON/OFF	Preset output	Usual control	If sensor is burnt out, the unit maintains control with the preset MV.	
	005	Preset output 2 ON/OFF	Preset output	Usual control	The unit maintains control with the preset MV.	
	005	Auto/Manual control (*2)	Manual	Automatic	Auto/Manual control selectable	
	007	Integral action Holding	Integral action	Usual integral	Control continues	
		(Stop)/Usual integral	Holding(Stop)	action	with the integral	
		action			value being held	
		Set value memory	SV1	SV2		
	009	Control ON/OFF (*1)	Control ON	Control OFF		
	0 0	Direct/Reverse action	Reverse	Direct		
		Preset output 1 ON/OFF	Usual control	Preset output		
	<u> </u>	Preset output 2 ON/OFF	Usual control	Preset output		
	<i>□0 13</i>	Auto/Manual control (*2)	Automatic	Manual		
	014	Integral action Holding (Stop)/Usual integral action	Usual integral action	Integral action Holding (Stop)		
		to $\square \square \square \square$ ?: Selected function to $\square \square \square$ / $\square$ : Selected function		•		
	in [Sl	n selecting Control ON/OFF JB-MODE key function], Eve n selecting Auto/Manual cor	ent input DI alloca	ation will return to	o No event.	
	. ,	JB-MODE key function], Eve				
<i>ЪД</i>	SV2				0°C	
	Sets S	V2 (the 2 <sup>nd</sup> desired value).				
		ble when Set value memory	external selectio	n (El option) is o	rdered.	
		ble when 001 or 008 is selec		· · /		
		range: Scaling low limit to S		-		

Character	Setting Item, Description, Setting Range	Factory Default
8 / 28	Alarm 1 value 0 Enabled/Disabled	Disabled
	Selects Alarm 1 action Enabled or Disabled when Alarm 1 value is 0	) (zero).
	• Not available if No alarm action is selected in [Alarm 1 type].	. ,
	<ul> <li>Invalidated for Process alarm</li> </ul>	
	• Disabled	
	₩E habled	
B IH	Alarm 1 high limit alarm value	<b>0</b> °C
	Sets Alarm 1 high limit alarm value.	
	Available when 'High/Low limits independent alarm', 'High/Low limit ra	ange independent
	alarm' or 'High/Low limits with standby independent alarm' is selected	d in [Alarm 1 type].
	• Setting range: See (Table 5.2-1) on p.13. (For DC voltage and curre	nt input, the
	placement of the decimal point follows the selection)	
AL 2F	Alarm 2 type	No alarm action
	Selects an Alarm 2 type.	
	Note: If Alarm 2 type is changed, Alarm 2 value returns to 0 (0.0).	
	•: No alarm action	
	High limit alarm	
	Low limit alarm	
	HL	
	$\vec{\omega} = \vec{\omega}$ High/Low limit range alarm	
	유너지. Process high alarm	
	$H \square \tilde{\omega}$ : High limit with standby alarm	
	$L \square \tilde{\omega}$ : Low limit with standby alarm	
	$HL \square \tilde{\omega}$ : High/Low limits with standby alarm	
	/ HL □: High/Low limits independent alarm	
	$H = \frac{1}{2}$ High/Low limits with standby independent alarm	
8258	Alarm 2 value 0 Enabled/Disabled	Disabled
, , <u>,</u> _ , ,	Selects Alarm 2 action Enabled or Disabled when Alarm 2 value is 0	
	• Not available if No alarm action is selected in [Alarm 2 type].	(2010).
	<ul> <li>Invalidated for Process alarm</li> </ul>	
82	Alarm 2 value	0°C
	Sets Alarm 2 action point.	-
	Alarm 2 value matches Alarm 2 low limit alarm value in the following	cases:
	When 'High/Low limits independent alarm', 'High/Low limit range ind	
	or 'High/Low limits with standby independent alarm' is selected in [A	larm 2 type].
	• When Alarm, Loop break alarm and Heater burnout alarm are used	together, they
	utilize common output terminals.	
	<ul> <li>Not available if No alarm action is selected in [Alarm 2 type].</li> </ul>	
	• Setting range: See (Table 5.2-1) on p.13. (For DC voltage, current ir	nput, the
	placement of the decimal point follows the selection.)	
82H[]	Alarm 2 high limit alarm value	<b>0</b> °C
	Sets Alarm 2 high limit alarm value.	
	<ul> <li>Available when 'High/Low limits independent alarm', 'High/Low limit rate</li> </ul>	•
	alarm' or 'High/Low limits with standby independent alarm' is selecte	
	• Setting range: See (Table 5.2-1) on p.13. (For DC voltage, current in	nput, the
	placement of the decimal point follows the selection)	

Character	Setting Item, Description, Setting Range	Factory Default
RZLA	Alarm 2 Energized/De-energized	Energized
	• Selects Alarm 2 action Energized/De-energized. (For details, see p. <sup>2</sup>	18.)
	Not available if No alarm action is selected in [Alarm 2 type].	
	• nañt : Energized	
	ィE 岩 <sup>-</sup> : De-energized	
R2Hd	Alarm 2 HOLD function	Not holding
	<ul> <li>Selects either Holding or Not holding in Alarm 2.</li> </ul>	
	When "Holding" is set, once alarm is activated, the alarm output rer	mains ON
	until the power is turned off.	
	<ul> <li>Not available if No alarm action is selected in [Alarm 2 type].</li> </ul>	
	・ ヮヮヮを: Not holding	
	HoLd: Holding	
RZHY	Alarm 2 hysteresis	1.0℃
	Sets Alarm 2 hysteresis.	
	<ul> <li>Not available if No alarm action is selected in [Alarm 2 type].</li> </ul>	
	Setting range:	
	Thermocouple, RTD input: 0.1 to 100.0℃(℉)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	point follows the
	selection.)	
82d¥	Alarm 2 delay time	0 sec
	Sets Alarm 2 action delay time.	
	When the setting time has elapsed after the input enters the alarm	output range,
	the alarm is activated.	
	<ul> <li>Not available if No alarm action is selected in [Alarm 2 type].</li> </ul>	
	Setting range: 0 to 9999 seconds	
RL 3F	Alarm 3 type	No alarm action
	• Selects an Alarm 3 type.	
	Note: If Alarm 3 type is changed, Alarm 3 value returns to 0 (0.0	D).
	• : No alarm action	
	High limit alarm	
	L Low limit alarm	
	HL: High/Low limits alarm	
	ul d High/Low limit range alarm	
	月っ二: Process high alarm	
	$r \overline{B}'$ Process low alarm	
	$H$ $\tilde{\omega}$ : High limit with standby alarm	
	L Low limit with standby alarm	
	HL DJ: High/Low limits with standby alarm	
	<i>HL</i> : High/Low limits independent alarm	
	$i \; \vec{\omega} i \; \vec{d}$ : High/Low limit range independent alarm	
RJER	<i>I HL ū</i> : High/Low limits with standby independent alarm <b>Alarm 3 value 0 Enabled/Disabled</b>	Disabled
// <u>_/</u> _//		
	<ul> <li>Selects Alarm 3 action Enabled or Disabled when Alarm 3 value is 0</li> <li>Not available if No alarm action is selected in [Alarm 3 type].</li> </ul>	
	<ul> <li>Invalidated for Process alarm</li> </ul>	
	• Invalidated for Process alarm	

Character	Setting Item, Description, Setting Range	Factory Default			
<i>R 3</i> [[]]]	Alarm 3 value	<b>0</b> °C			
	Sets Alarm 3 action point.				
	Alarm 3 value matches Alarm 3 low limit alarm value in the following	g cases:			
	When 'High/Low limits independent alarm', 'High/Low limit range independent alarm'				
	or 'High/Low limits with standby independent alarm' is selected in [Alarm 3 type].				
	• When Alarm, Loop break alarm and Heater burnout alarm are used together, they				
	utilize common output terminals.				
	• Not available if No alarm action is selected in [Alarm 3 type].				
	• Setting range: See (Table 5.2-1) on p.13. (For DC voltage, current	input, the			
	placement of the decimal point follows the selection.)	<b>-</b> <sup>2</sup> C			
R 3 H 🗌	Alarm 3 high limit alarm value	0°C			
	Sets Alarm 3 high limit alarm value.				
	• Available when 'High/Low limits independent alarm', 'High/Low limit i	•			
	alarm' or 'High/Low limits with standby independent alarm' is selected	ed in [Alarm 3 type].			
	• Setting range: See (Table 5.2-1) on p.13.	allows the			
	(For DC voltage, current input, the placement of the decimal point for selection)	blows the			
ABLA		Energized			
, , _, <u>,</u> , ,	<ul> <li>Alarm 3 Energized/De-energized</li> <li>Selects Alarm 3 action Energized/De-energized. (For details, see p.</li> </ul>	Energized			
	<ul> <li>Not available if No alarm action is selected in [Alarm 3 type].</li> </ul>	10.)			
	י הבהג: Energized				
	- Ε Η -: De-energized				
ЯЗНЫ	Alarm 3 HOLD function	Not holding			
	Selects either Holding or Not holding in Alarm 3.				
	When "Holding" is set, once alarm is activated, the alarm output rei	mains ON			
	until the power is turned off.				
	• Not available if No alarm action is selected in [Alarm 3 type].				
	・ ヮヮヮE : Not holding				
	Holding				
83XY	Alarm 3 hysteresis	1.0℃			
	Sets Alarm 3 hysteresis.				
	• Not available if No alarm action is selected in [Alarm 3 type].				
	Setting range:				
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)				
	DC voltage, current input: 1 to 1000 (The placement of the decimal	point follows the			
	selection.)	1			
8349	Alarm 3 delay time	0 sec			
	Sets Alarm 3 action delay time.				
	When the setting time has elapsed after the input enters the alarm	output range, the			
	alarm is activated.				
	• Not available if No alarm action is selected in [Alarm 3 type].				
	Setting range: 0 to 9999 seconds				

Character	Setting Item, Description, Setting Range	Factory Default
RL YF	Alarm 4 type	No alarm action
	Selects an Alarm 4 type.	
	Note: If Alarm 4 type is changed, Alarm 4 value returns to 0 (0.0	D).
	• : No alarm action	-
	High limit alarm	
	L Low limit alarm	
	HL High/Low limits alarm	
	ພ້¦ d⊡: High/Low limit range alarm	
	R'- Process high alarm	
	<i>-                                    </i>	
	$H \square \tilde{\omega}$ : High limit with standby alarm	
	L Low limit with standby alarm	
	$HL \square \overline{\omega}$ : High/Low limits with standby alarm	
	/ HL : High/Low limits independent alarm	
	$i  \bar{\omega} i  d$ : High/Low limit range independent alarm	
	$HL \tilde{\omega}$ : High/Low limits with standby independent alarm	
8438	Alarm 4 value 0 Enabled/Disabled	Disabled
	Selects Alarm 4 action Enabled or Disabled when Alarm 4 value is	0 (zero).
	Not available if No alarm action is selected in [Alarm 4 type].	
	Invalidated for Process alarm	
	・ ロロ Disabled	
	ビビット Enabled	
84	Alarm 4 value	<b>0</b> °C
	Sets Alarm 4 action point.	
	Alarm 4 value matches Alarm 4 low limit alarm value in the following	g cases:
	When 'High/Low limits independent alarm', 'High/Low limit range inc	dependent alarm'
	or 'High/Low limits with standby independent alarm' is selected in [A	larm 4 type].
	• When Alarm, Loop break alarm and Heater burnout alarm are used	together, they
	utilize common output terminals.	
	• Not available if No alarm action is selected in [Alarm 4 type].	
	• Setting range: See (Table 5.2-1) on p.13. (For DC voltage, current i	nput, the
· · · · · · · · · · · · · · · · · · ·	placement of the decimal point follows the selection.)	1
ЯЧН[]	Alarm 4 high limit alarm value	0°C
	Sets Alarm 4 high limit alarm value.	
	Available when 'High/Low limits independent alarm', 'High/Low limit r	•
	alarm' or 'High/Low limits with standby independent alarm' is selected	
	• Setting range: See (Table 5.2-1) on p.13. (For DC voltage, current i	nput, the
	placement of the decimal point follows the selection)	
84LA	Alarm 4 Energized/De-energized	Energized
	Selects Alarm 4 action Energized/De-energized. (For details, see p.1	18.)
	• Not available if No alarm action is selected in [Alarm 4 type].	
	• nonit: Energized	
	$r \in E \cup E$ De-energized	
ЯЧНЫ	Alarm 4 HOLD function	Not holding
	Selects either Holding or Not holding in Alarm 4.	
	When "Holding" is set, once alarm is activated, the alarm output rer	nains ON
	until the power is turned off.	
	• Not available if No alarm action is selected in [Alarm 4 type].	
	• nenE: Not holding	
	Holding	

Character	Setting Item, Description, Setting Range	Factory Default
ЯЧНУ	Alarm 4 hysteresis	1.0°C
	Sets Alarm 4 hysteresis.	
	Not available if No alarm action is selected in [Alarm 4 type].	
	Setting range:	
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	point follows the
	selection.)	
8439	Alarm 4 delay time	0 sec
	Sets Alarm 4 action delay time.	
	When the setting time has elapsed after the input enters the alarm	output range, the
	alarm is activated.	
	Not available if No alarm action is selected in [Alarm 4 type].	
	Setting range: 0 to 9999 seconds	<u> </u>
-EAC	Remote/Local	Local
	Selects Remote (Remote operation) or Local (keypad operation) se	tting of the SV.
	• Available only when External setting input (EA option) is ordered.	
	• LgcL: Local	
	<i>⊂ E ດັໂ</i> : Remote	
-F_b	Remote bias	<b>0</b> ℃
	Sets the remote bias value.	
	During remote action, the remote bias value is added to control des	ired value.
	• Available only when External setting input (EA option) is ordered.	
, , ,	Setting range: ±20% of input span	
$-\Gamma L H$	External setting input high limit	1370℃
	Sets External setting input high limit value.	
	• Available only when External setting input (EA option) is ordered.	
, , ,	Setting range: External setting input low limit to Scaling high limit	
FFLL	External setting input low limit	<b>–200</b> ℃
	Sets External setting input low limit value.	
	• Available only when External setting input (EA option) is ordered.	
	Setting range: Scaling low limit to External setting input high limit	
- <i>8</i> 55	SV Rise/Fall rate start type	SV start
	• Selects SV or PV start for the SV ramp function.	
	・ <i>与皆与</i> だ : SV start <i>や皆っ</i> だ : PV start	
-860	SV rise rate	0 ℃/minute
	Sets SV rise rate (rising value for 1 minute).	0 C/minute
	• Setting to 0 (zero) disables this function.	
	• Setting range: 0 to 9999 °C/min (°F/min) (The placement of the deci	mal point follows
	the selection.)	
	Thermocouple, RTD input: 0.0 to 999.9 °C/min (°F/min)	
	DC voltage, current input: 0 to 9999/min	
- AF d	SV fall rate	0 °C/minute
_	Sets SV fall rate (falling value for 1 minute).	
	• Setting to 0 (zero) disables this function.	
	• Setting range: 0 to 9999 $^{\circ}$ C/min ( $^{\circ}$ F/min) (The placement of the deci	mal point follows
	the selection.)	
	Thermocouple, RTD input: 0.0 to 999.9 °C/min (°F/min)	
	DC voltage, current input: 0 to 9999/min	

Character	Setting Item, Description, Setting Range	Factory Default				
Poll	Control output OUT1/EVT	OUT1				
	OUT1 or EVT terminals can be selected for control output OUT1.					
	If OUT1 is selected, the output terminals will be as follows.					
	Control output OUT1: O1 terminals (3-4)					
	Event output: EV terminals (8)-9)					
	If EVT is selected, output terminals will be as follows.					
	Control output OUT1: EV terminals (⑧-⑨)					
	Event output: O1 terminals (③-④)					
	Select $EBT$ (EVT) if control output OUT1 is used as Open colle	ctor output.				
	Not available for direct current output.					
	・ <i>ヮU「</i> /: OUT1					
		1				
Hohl	Heater burnout alarm output Enabled/Disabled	Enabled				
	<ul> <li>Selects whether EVT output is used for Heater burnout alarm output</li> </ul>					
	If Heater burnout alarm, Loop break alarm and Alarm (1-4) output a	are set to				
	"Enabled", they utilize common output terminals.					
	• Available only when Heater burnout alarm (W option) is ordered.					
, , , ,	<u> 46'5</u> : Enabled					
LP4L	Loop break alarm output Enabled/Disabled	Enabled				
	• Selects whether EVT output is used for Loop break alarm output.					
	If Loop break alarm, Heater burnout alarm and Alarm (1 - 4) output	are set to				
	"Enabled", they utilize common output terminals.					
	Available only when Heating/Cooling control (DC option) is ordered.					
	・ ロロー: Disabled, ゴミトー: Enabled					
8 156	Alarm 1 output Enabled/Disabled	Enabled				
	•	LIIADIEU				
	• Selects whether EVT output is used for Alarm 1 output. If Loop break alarm, Heater burnout alarm, Alarm 2, Alarm 3 and Alarm 4 output are					
	set to "Enabled", they utilize common output terminals.					
	Not available if Heating/Cooling control (DC option) is ordered.					
	יווטי מעמומטופ א אופט נטאוט (בי גער מעמונט א אופט גער אין א גער					
8246	Alarm 2 output Enabled/Disabled	Disabled				
	Selects whether EVT output is used for Alarm 2 output.					
	If Loop break alarm, Heater burnout alarm, Alarm 1, Alarm 3 and Alarm 4 output are					
	set to "Enabled", they utilize common output terminals.					
	• Not available if Heating/Cooling control (DC option) is ordered.					
	• ng[]: Disabled					
	<i>当と</i> ら[]: Enabled					
8346		Disabled				
8341	Alarm 3 output Enabled/Disabled	Disabled				
8341	Alarm 3 output Enabled/Disabled • Selects whether EVT output is used for Alarm 3 output.					
8351	<ul> <li>Alarm 3 output Enabled/Disabled</li> <li>Selects whether EVT output is used for Alarm 3 output.</li> <li>If Loop break alarm, Heater burnout alarm, Alarm 1, Alarm 2 and Al</li> </ul>					
8341	<ul> <li>Alarm 3 output Enabled/Disabled</li> <li>Selects whether EVT output is used for Alarm 3 output. If Loop break alarm, Heater burnout alarm, Alarm 1, Alarm 2 and Al set to "Enabled", they utilize common output terminals.</li> </ul>					
8341	<ul> <li>Alarm 3 output Enabled/Disabled</li> <li>Selects whether EVT output is used for Alarm 3 output.</li> <li>If Loop break alarm, Heater burnout alarm, Alarm 1, Alarm 2 and Al</li> </ul>					

Character	Setting Item, Description, Setting Range	Factory Default				
RYSL	Alarm 4 output Enabled/Disabled	Disabled				
	Selects whether EVT output is used for Alarm 4 output.					
	If Loop break alarm, Heater burnout alarm, Alarm 1, Alarm 2 and Al	arm 3 output are				
	set to "Enabled", they utilize common output terminals.	•				
	• Not available if Heating/Cooling control (DC option) is ordered.					
	• ng Disabled					
	<i>当とら</i> Enabled					
P46 (	OUT1 MV Preset value	0.0%				
	• Sets OUT1 MV preset value when Preset output 1 or 2 is selected i	n [Event input DI				
	allocation].					
	Function 1: Outputs OUT1 MV preset value when Event input DI is a	closed and				
	sensor is burnt out.					
	Function 2: Outputs OUT1 MV preset value when Event input DI is a	closed.				
	Available only when Set value memory external selection (EI option	) is ordered				
	0.0% or 100.0% for ON/OFF control					
	Setting range: OUT1 low limit to OUT1 high limit	-				
PSFZ	OUT2 MV Preset value	0.0%				
	Sets OUT2 MV preset value when Preset output 1 or 2 is selected in [Event input DI					
	allocation].					
	Function 1: Outputs OUT2 MV preset value when Event input DI is closed and					
	sensor is burnt out.					
	Function 2: Outputs OUT2 MV preset value when Event input DI is o					
	Available when Set value memory external selection (EI option) or Heating/Cooling					
	control (DC option) is ordered.					
	0.0% or 100.0% for ON/OFF control action					
	Setting range: OUT2 low limit to OUT2 high limit					
ā8n∐	SUB-MODE key function	Control output				
	Selects a function of the SUB-MODE key from the following:	OFF				
	Control output OFF, Auto/Manual control, Alarm HOLD cancel					
	• $\Box F F \Box$ : Control output OFF					
	ก็∺ิกป: Auto/Manual control					
,	RL oF: Alarm HOLD cancel					
	Auto/Manual control after power ON	Automatic control				
	• When the power is turned ON, Automatic control or Manual control	can be selected				
	for starting control.					
	• Available only when 'Auto/Manual control' is selected in [SUB-MOD	E Key function].				
	• RUF : Automatic control					
	ດ້ອີດປິ: Manual control					

#### 5.6 Output MV (manipulated variable) Indication

Description				
Output MV (manipulated variable) indication				
Press the 💭 key for approx. 3 seconds in PV/SV Display mode.				
Keep pressing the 💭 key until the output manipulated variable appears, though the main setting				
mode appears during the process.				
The output MV is indicated on the SV Display, and the 1st decimal point from the right flashes				
in 500 ms cycles on the SV Display.				
If the 💭 key is pressed again, the instrument reverts to PV/SV Display mode.				

### 6. Simplified Converter Function

### ▲ Caution

- The converter function is selectable only for the Direct current output type.
- When using this controller as a converter, take 1 second into consideration since input/output response time is approx. 1 second.
- When switching from converter to controller function, the control parameters and values set by converter function are retained even if the function is switched to controller function. So, after switching to the controller function, correct the converter parameters to the controller parameters.

The converter function of this instrument converts each input (thermocouple, RTD, DC voltage and direct current input) value to "4 to 20 mA DC", using the control parameters of the controller, and outputs it.

When this instrument is used as a converter, follow steps (1) to (7) described below. After steps (1) to (7) are finished, this instrument can be used as a converter.

- (1) Wire this unit (Power supply, Input and Output).
- (2) Turn the power supply of this unit ON.
- (3) Enter 'Auxiliary function setting mode 2' by pressing the  $\bigcirc$  and  $\bigcirc$  key (for approx. 3 sec).
- (4) Select a sensor type in [Input type]  $(\neg \not \vdash \neg \neg)$ .
- (5) Set the high limit of the value to be converted in [Scaling high limit]  $(\neg f \downarrow H)$ ".
- (6) Set the low limit of the value to be converted in [Scaling low limit]  $(\neg f \downarrow \downarrow)$ ".
- (7) Select Converter  $(\Box \Box \Box' \Box')$  in [Controller/Converter]  $(F \Box \Box \Box)$ .

#### • To activate the alarm action by Converter function, set the alarm type to Process alarm.

If 'Converter' is selected in [Controller/Converter] in Auxiliary function setting mode 2, parameters below are automatically set. (Table 6-1)

Setting Item	Setting Value		
SV1	Scaling low limit		
SV2	Scaling low limit		
Integral time	0		
Derivative time	0		
OUT1 proportional band	100.0%		
OUT2 proportional band	1.0		
Manual reset	0.0		
Alarm 1 value 0 Enabled/Disabled	Disabled		
Alarm 1 value	0		
Alarm 1 high limit alarm value	0		
Alarm 2 value 0 Enabled/Disabled	Disabled		
Alarm 2 value	0		
Alarm 2 high limit alarm value	0		
Alarm 3 value 0 Enabled/Disabled	Disabled		
Alarm 3 value	0		
Alarm 3 high limit alarm value	0		
Alarm 4 value 0 Enabled/Disabled	Disabled		
Alarm 4 value	0		
Alarm 4 high limit alarm value	0		
Loop break alarm time	0		
Loop break alarm span	0		
Direct/Reverse action	Direct action		
Event input DI allocation	000		

#### (Table 6-1)

Setting Item	Setting Value
Remote/Local (El option)	Local
SV rise rate	0
SV fall rate	0
OUT1 high limit	100
OUT1 low limit	0
Alarm 1 to Alarm 4 types	No alarm action
Alarm 1 hysteresis	1.0
Alarm 1 delay time	0
Alarm 1 Energized/De-energized	Energized
Alarm 2 hysteresis	1.0
Alarm 2 delay time	0
Alarm 2 Energized/De-energized	Energized
Alarm 3 hysteresis	1.0
Alarm 3 delay time	0
Alarm 3 Energized/De-energized	Energized
Alarm 4 hysteresis	1.0
Alarm 4 delay time	0
Alarm 4 Energized/De-energized	Energized

#### 6.1 Fine Adjustment of Converter Output (4 to 20 mA DC)

Outputs "4 to 20 mA DC" corresponding to the input from scaling low limit to high limit value. Fine adjustment rate is 1/1000 of the scaling span.

#### Fine adjustment method

Be sure to adjust the zero side first. Then adjust the span side.

#### (1) Zero adjustment

- ① Enter the value so that the PV Display can indicate the same value as the scaling low limit value.
- $^{(2)}$  Press the  $\bigtriangleup$  and  $\boxdot$  key (in that order). The unit proceeds to Sub setting mode.
- ③ Press the  $\bigcirc$  key several times until "Manual reset ( $\neg \neg \xi \Gamma$ )" appears.
- ④ Adjust the converter output value so that it can become 4 mA DC by increasing and decreasing the value with △ and ▽ keys.

Pressing the  $\bigtriangleup$  key decreases the value, and the  $\bigtriangledown$  key increases it.

<sup>⑤</sup> Revert to the PV/SV Display mode by pressing the  $\bigcirc$  key several times.

#### (2) Span adjustment

- ① Enter the value so that the PV Display can indicate the same value as the scaling high limit value.
- $^{(2)}$  Press the  $\bigtriangleup$  and  $\boxdot$  key (in that order). The unit proceeds to Sub setting mode.
- ③ Proceed to the "Proportional band (*P* by pressing the  $\square$  key.
- ④ Adjust the converter output value so that it can become 20 mA DC by increasing and decreasing the value with the △ and ▽ keys.
  - Pressing the  $\bigtriangleup$  key decreases the value, and the  $\bigtriangledown$  key increases it.
- <sup>⑤</sup> Revert to the PV/SV Display mode by pressing the 💭 key several times.

#### (3) Repeat steps (1) and (2) several times.

#### 6.2 Converter Setting Example

#### [Other Inputs except 4 to 20 mA DC]

#### Input, output conditions

```
Input: 6 to 14 mA DC (Indication: 30.0 to 130.0)
Output: 4 to 20 mA DC
```

#### Setting method

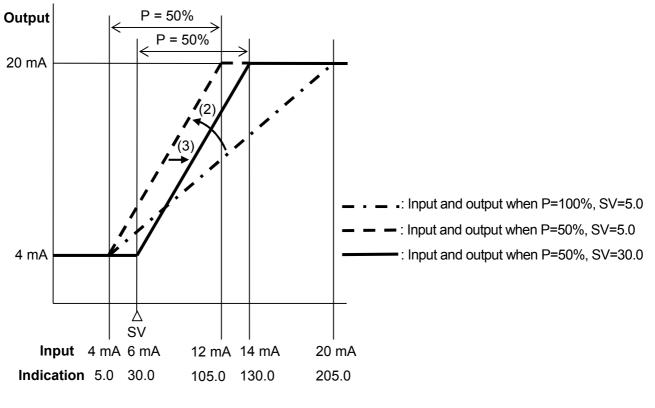
#### (1) Calculating Scaling high and low limit value of 4 to 20 mA DC

Indication value per mA DC:  $(130.0 - 30.0) \div (14 - 6) = 100 \div 8 = 12.5$ Scaling high limit value:  $130.0 + (20 - 14) \times 12.5 = 205.0$ Scaling low limit value:  $30.0 - (6 - 4) \times 12.5 = 5.0$ 

- (2) Calculating OUT proportional band of 6 to 14 mA DC OUT proportional band (P) =  $\{(14 - 6) \div (20 - 4)\} \times 100 = 0.5 \times 100 = 50$  (%)
- (3) Calculating SV so that output can become 4 mA DC from 6 mA DC input (Parallel shift setting)

 $SV = \{(6-4) \times 12.5\} + 5.0$  (Scaling low limit) = 30.0

#### Input, output and indication



(Fig. 6.2-1)

### 7. Operation

After the unit is mounted within the control panel (DIN rail) and wiring is completed, operate the unit following the procedure below.

#### (1) Turn the power supply to the DCL-33A ON.

For approx. 3 seconds after power is turned on, sensor input characters and temperature unit are indicated on the PV Display, and the input range high limit value is indicated on the SV Display. See (Table 5-1) on p.11. During this time, all outputs and LED indicators are in OFF status. (If any other value is set in [Scaling high limit], the SV Display indicates it.) After that, the PV Display indicates PV (process variable), and the SV Display indicates SV (desired value).

#### (2) Enter each set value.

Enter each set value, referring to "5. Setup".

#### (3) Turn the load circuit power ON.

Control action starts so as to keep the control target at the SV (desired value).

#### **SUB-MODE Key Function**

The SUB-MODE key function differs depending on the selection in [SUB-MODE key function].

#### • If 'Control output OFF' is selected:

The control action and output of an instrument (or instruments) can be turned OFF without turning OFF their power supplies using this function.

If the control output OFF function is enabled, and the PV Display will indicate  $\alpha FF$ , turning all outputs OFF.

To enable the control output OFF function, press the SUB-MODE key for approximately 1 second in PV/SV Display mode.

To enable the control output OFF function, press the SUB-MODE key for approximately 3 seconds in setting mode.

If the SUB-MODE key is pressed for approximately 1 second again, the function will be cancelled, and the unit will return to PV/SV Display mode.

#### • If 'Auto/Manual control' is selected:

Auto/Manual control can be switched.

Each time the SUB-MODE key is pressed for approximately 1 second in PV/SV Display mode, Automatic or Manual control can be switched.

#### • If 'Alarm HOLD cancel' is selected:

Alarm Hold can be cancelled for the Alarm with Hold function.

To enable the Alarm HOLD cancel function, press the SUB-MODE key for approximately 1 second in PV/SV Display mode.

To enable the Alarm HOLD cancel function, press the SUB-MODE key for approximately 3 seconds in setting mode.

#### **Event Input**

Event Input DI action has priority over key operation.

#### Set value memory external selection (El option)

By closing or opening the Event Input DI contact, SV1 and SV2 can be selected.
Depending on the selection in [Event input DI allocation], the following differences result in:
If 001 (Set value memory) is selected in [Event input DI allocation]:
Event input DI Open: SV1
Event input DI Closed: SV2
If 008 (Set value memory) is selected in [Event input DI allocation]:
Event input DI Open: SV1
Event input DI Closed: SV2
If 008 (Set value memory) is selected in [Event input DI allocation]:
Event input DI Open: SV2
Event input DI Open: SV1

## 8. Action Explanations 8.1 OUT1 Action

	Heating (Reverse) action	Cooling (Direct) action		
Control action	ON Proportional band OFF A	Proportional band ON OFF SV		
Relay contact output	3 4 Cycle action is performed according to deviation	3 4 Cycle action is performed according to deviation		
Non- contact voltage output	$\begin{array}{c c} + 3 & + 3 & + 3 \\ 12 \text{ V DC} & 12/0 \text{ V DC} & 0 \text{ V DC} \\ - 4 & - 4 & - 4 & - 4 \\ \hline \end{array}$ Cycle action is performed according to deviation	$\begin{array}{c c} + 3 & + 3 & + 3 \\ 0 \lor DC & 0/12 \lor DC \\ - 4 & - 4 & - 4 \\ \hline Cycle action is performed \\ according to deviation \end{array}$		
Direct current output	$\begin{array}{c c} + 3 & + 3 & + 3 \\ 20 \text{ mA DC} & 20 \text{ to 4 mA DC} & 4 \text{ mA DC} \\ - 4 & - 4 & - 4 & - 4 \\ \hline \\ Changes continuously \\ according to deviation \end{array}$	$\begin{array}{c c} + 3 & + 3 & + 3 \\ 4 & \text{mA DC} & 4 & \text{to 20 mA DC} \\ - 4 & - 4 & - 4 & - 4 \\ \end{array} \begin{array}{c} + 3 & - 4 & - 4 \\ 20 & \text{mA DC} & - 4 & - 4 \\ - 4 & - 4 & - 4 & - 4 \\ \end{array}$ Changes continuously according to deviation		
Indicator (OUT) Green	Lit Unlit	Unlit Lit		

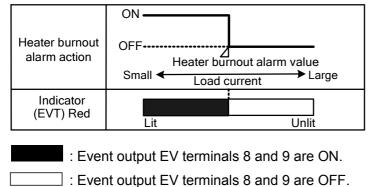
: Turns ON or OFF.

#### 8.2 OUT1 ON/OFF Control Action

	Heating (Reverse) action			Cooling (Direct) action		
Control action	ON	Hysteresis		2	Hysteresis	ON OFF
Relay contact output	3 		<sup>3</sup> ~ 4	3 		() () ()
Non-contact voltage output	+ 3 12 V DC - 4		+3 0 V DC -4	+ 3 0 V DC - 4		+3 12 V DC -4
Direct current output	+ 3 20 mA DC - 4		+ 3	+ 3 4 mA DC - 4		+3 20 mA DC - 4
Indicator (OUT) Green	Lit		Unlit	Unlit		Lit

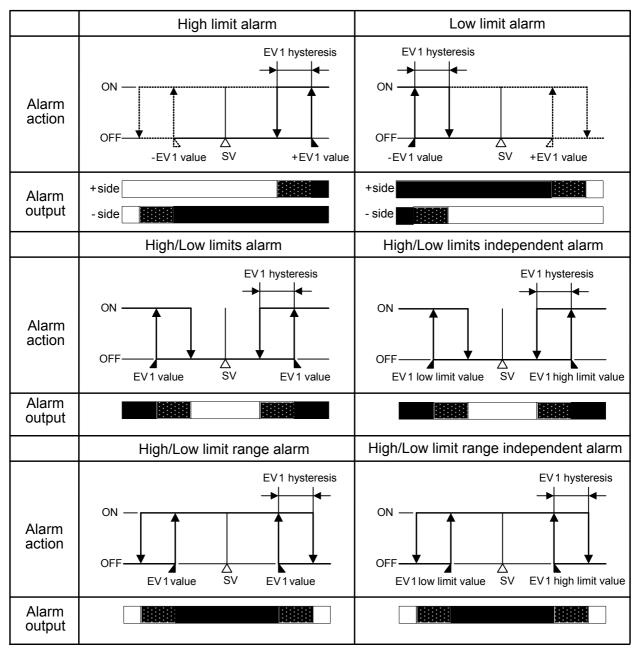
: Turns ON or OFF.

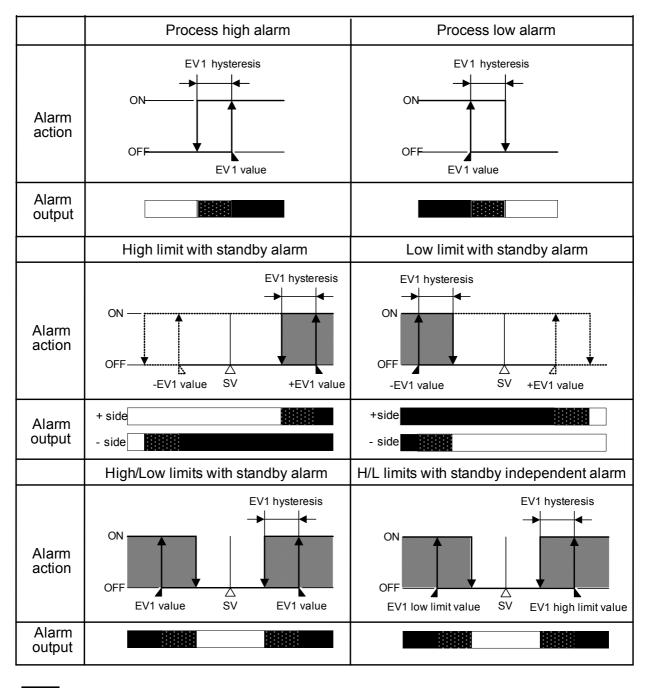
#### 8.3 Heater Burnout Alarm Action



The Event output EVT indicator lights up when Event output EV terminals 8 and 9 are ON, and turns off when they are OFF.

#### 8.4 Alarm Action







: Event output EV terminals 8 and 9 are ON.

: Event output EV terminals 8 and 9 are ON or OFF.

: Event output EV terminals 8 and 9 are OFF.

: Alarm output is in Standby.

The Event output EVT indicator lights up when Event output EV terminals 8 and 9 are ON, and turns off when they are OFF.

#### 8.5 OUT2 Action

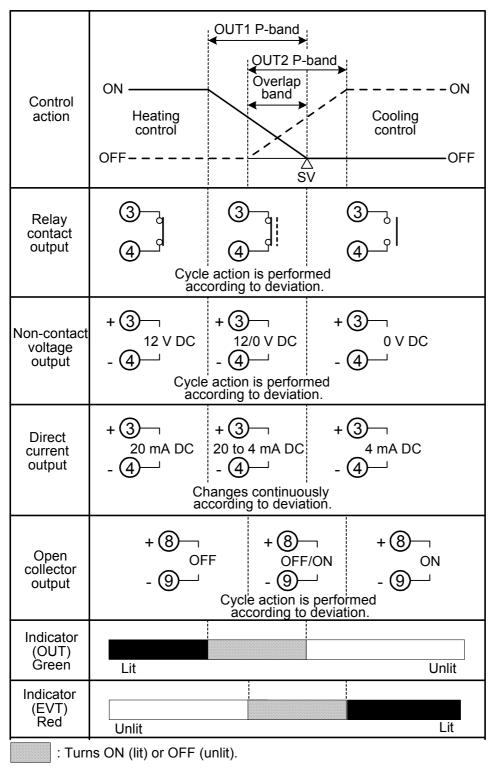
	OUT1 P-band OUT2 P-band					
Control action	ON Heating action			Cooling action OFF		
		S	2 V	UFF		
Relay contact	3_	<del>®_</del>	<sup>®</sup>			
output	 دې	d cle action is perforr ccording to deviatio	(4)⁰ I ned			
	+3	+ 3	+3-			
Non-contact voltage output	- (4)	- (4)'	- (4)'			
	Cyc	cle action is perform	ned n.			
Direct current output	+ 3	+ 3 20 to 4 mA DC - 4	+ 3 4 mA DC - 4			
- and a -	с С	hanges continuous	v Č			
		+ 8-	+ 8-	+ 8–		
Open collector output		0FF - ⑨—	OFF/ON - 9	on - ⑨─┘		
		cle action is perform ccording to deviatio	ned n.			
Indicator (OUT) Green	Lit			Unlit		
Indicator (EVT) Red	Unlit			Lit		
	Offine			LIL		

: Turns ON (lit) or OFF (unlit).

------ : Represents Heating control action.

----- : Represents Cooling control action.

#### 8.6 OUT2 Action (When Setting Overlap Band)



- : Represents Heating control action.

----- : Represents Cooling control action.

#### 8.7 OUT2 Action (When Setting Dead Band)

		OUT1 P-band	Dead band	(OUT2 P-band)		
	ON		,		C	DN
Control	Heating				Cooling	
action	action				action	
	OFF				0	FF
		SV				
Relay	() (3- <sub>q</sub>	3 <sub>9</sub>	<sub>ا</sub> ه ®			
contact output	<u>م</u>	പ്	ഘി			
output		le action is performed cording to deviation.				
	+3-	+ 3	+(3)			
Non-contact voltage	12 V DC	12/0 V DC				
output	- (4)	- ④	- 4—			
	ac	le action is performed cording to deviation.				
Direct	+3¬	+ 3-	+3-			
current	20 mA DC	20 to 4 mA DC	4 mA DC			
output	- (4)—' <sub>Ch</sub>	- (4)—	- (4)—			
	ac	nanges continuously cording to deviation.				
			+ 🛞 🖳	+ 8-	+ 🛞 🖳	
Open collector			OFF	OFF/ON	ON	
output			- (9)' <sub>C</sub>	ycle action is perform according to deviatio	- (9)—' ned	
		I		according to deviatio	n.	
Indicator (OUT)				-		]
Green	Lit				Unlit	
Indicator (EVT)						
Red	Unlit				Lit	
L	1					

: Turns ON (lit) or OFF (unlit).

-

------ : Represents Heating control action.

----- : Represents Cooling control action.

# 9. AT (Auto-tuning)

In order to decide each value of P, I, D and ARW automatically, the auto-tuning process should be made to fluctuate to obtain an optimal value.

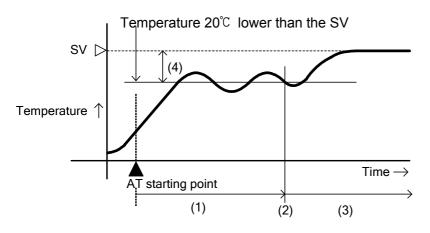
One of 3 types of fluctuation below is automatically selected.

For DC input, the AT process will fluctuate around the SV for conditions of (A), (B) and (C).

# Sometimes the auto-tuning process will not fluctuate if auto-tuning is performed at or near room temperature. Therefore auto-tuning might not finish normally.

# (A) In the case of a large difference between the SV and processing temperature as the temperature is rising

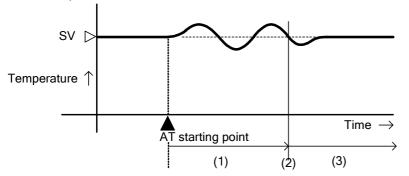
When AT bias is set to 20°C, the AT process will fluctuate at temperatures 20°C lower than the SV.

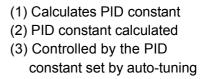


(1) Calculates PID constant
 (2) PID constant calculated
 (3) Controlled by the PID constant set by auto-tuning
 (4) AT bias value

#### (B) When control is stable

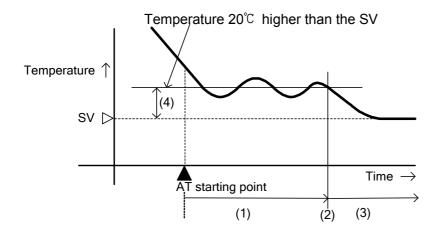
The AT process will fluctuate around the SV.





# (C) In the case of a large difference between the SV and processing temperature as the temperature is falling

When AT bias is set to 20°C, the AT process will fluctuate at temperatures 20°C higher than the SV.



(1) Calculates PID constant
 (2) PID constant calculated
 (3) Controlled by the PID constant set by auto-tuning
 (4) AT bias value

# 10. Specifications

#### 10.1 Standard Specifications

Model: DIN rail mounted indicating controller

Mounting: DIN rail

**Setting:** Input system using membrane sheet key

Display:

PV Display: Red LED 4 digits, character size 7.4 x 4.0 mm (H x W)

SV Display: Green LED 4 digits, character size 7.4 x 4.0 mm (H x W)

#### Input:

Thermocouple: K, J, R, S, B, E, T, N, PL-II, C (W/Re5-26) External resistance: 100  $\Omega$  max. However, for thermocouple B, external resistance: 40  $\Omega$  max.

RTD: Pt100, JPt100, 3-wire type

Allowable input lead wire resistance (10  $\Omega$  max. per wire)

Direct current: 0 to 20 mA DC, 4 to 20 mA DC, input impedance 50  $\Omega$ 

If direct current input (Externally mounted 50  $\Omega$  shunt resistor) is designated, connect a 50  $\Omega$  shunt resistor (sold separately) between input terminals. Allowable input current: 50 mA max.

DC voltage:

	0 to 1 V DC	0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
Input impedance	$1 M\Omega$ min.	100 kΩ min.
Allowable input voltage	5 V max.	15 V max.
Allowable signal source resistance	2 kΩ max.	100 Ω max.

#### Indication performance:

Base accuracy (at ambient temperature 23°C, for a single unit mounting):

Thermocouple: Within  $\pm 0.2\%$  of input span  $\pm 1$  digit, or within  $\pm 2^{\circ}\mathbb{C}$  (4°F), whichever is greater R, S inputs, 0 to 200°C (0 to 400°F): Within  $\pm 6^{\circ}\mathbb{C}$  (12°F)

B input, 0 to  $300^{\circ}$ C (0 to  $600^{\circ}$ F): Accuracy is not guaranteed.

K, J, E, T, N input, less than  $0^{\circ}C$  (32°F):

Within  $\pm 0.4\%$  of input span  $\pm 1$  digit, or  $\pm 4^{\circ}$ C (8°F), whichever is greater

Within  $\pm 0.1\%$  of input span  $\pm 1$  digit, or within  $\pm 1^{\circ}$ C (2°F) whichever is greater

RTD: Within  $\pm 0.1\%$  of input span  $\pm 1$  digit, DC voltage: Within  $\pm 0.2\%$  of input span  $\pm 1$  digit

Direct current: Within  $\pm 0.2\%$  of input span  $\pm 1$  digit

Input sampling period: 125 ms

**Control performance:** Same as setting accuracy and base accuracy

#### Control action:

- PID control [with auto-tuning (AT) function]
- PI control: When derivative time is set to 0
- PD control (with manual reset function): When integral time is set to 0
- P control (with manual reset function): When derivative and integral time are set to 0
- ON/OFF control: When OUT1 proportional band is set to 0.0
- OUT1 proportional band: 0.0 to 110.0% (ON/OFF control when set to 0.0)
- Integral time: 0 to 3600 seconds (Disabled when set to 0)
- Derivative time: 0 to 1800 seconds (Disabled when set to 0)

OUT1 proportional cycle: 1 to 120 seconds

ARW: 0 to 100%

Manual reset: ±Proportional band converted value

OUT1 high, OUT1 low limit: 0 to 100% (Direct current output type: -5 to 105%)

(Not available for ON/OFF control)

OUT1 ON/OFF hysteresis: Thermocouple, RTD input: 0.1 to 100.0℃ (°F)

DC voltage, current input: 1 to 1000 (The placement of the

decimal point follows the selection.)

Control output (OUT):

• Relay contact: 1a, Control capacity: 3 A 250 V AC (Resistive load)

1 A 250 V AC (Inductive load  $\cos\phi$  = 0.4)

#### Electrical life: 100,000 cycles

- Non-contact voltage (for SSR drive): 12 V DC±15% Max. 40 mA DC (Short circuit protected)
- Direct current: 4 to 20 mA DC, Load resistance: Max. 550 Ω
  - Output accuracy: Within  $\pm 0.3\%$  of the output span Resolution: 12000

#### **EVT** output:

#### Alarm output

[Alarm, Loop break alarm and Heater burnout alarm (W option) utilize common output terminals.]

The alarm action point is set by  $\pm$  deviation from the SV (excluding Process alarm), and when input goes outside the range, alarm output is turned ON or OFF (High/Low limit range alarm). When De-energized is selected in [Alarm Energized/De-energized], alarm output is activated conversely.

Setting accuracy: Same as base accuracy

Action: ON/OFF action

Hysteresis: Thermocouple, RTD input: 0.1 to 100.0℃ (°F)

DC voltage, current input: 1 to 1000 (The placement of the decimal point follows the selection.)

Output: Open collector, Control capacity: 0.1 A 24 V DC

Alarm type: One alarm action can be selected from below by front keypad operation: High limit, Low limit, High/Low limits, High/Low limits independent alarm, High/Low limit range, High/Low limit range independent alarm, Process high, Process low, High limit with standby, Low limit with standby, High/Low limits with standby, High/Low limits with standby independent alarm, and No alarm action

The above 12 alarm types and No alarm action can be selected.

Energized/De-energized: Alarm (EVT) output Energized/De-energized can be selected.

	Energized	De-energized
EVT indicator (Red)	Lights up	Lights up
EVT output	ON	OFF

Alarm HOLD function: Once the alarm is activated, alarm output is maintained until the power is turned off.

#### Loop break alarm output

[Loop break alarm, Alarm and Heater burnout alarm (W option) utilize common output terminals.]

Detects heater burnout, sensor burnout and actuator trouble.

Setting range: Loop break alarm time: 0 to 200 minutes

Loop break alarm span:

Thermocouple, RTD input: 0 to  $150^{\circ}$ C (°F) or 0.0 to  $150.0^{\circ}$ C (°F) DC voltage, current input: 0 to 1500 (The placement of the decimal

point follows the selection.)

Output: Open collector, Control capacity: 0.1 A 24 V DC

Converter function: See "6. Simplified Converter Function".

#### Attached function:

[Set value lock]

[Sensor correction]

#### [Power failure countermeasure]

The setting data is backed up in non-volatile IC memory.

#### [Self diagnosis]

The CPU is monitored by a watchdog timer, and when an abnormal status is found on the CPU, the controller is switched to warm-up status turning all outputs off.

#### [Automatic cold junction temperature compensation] (Only thermocouple input)

Detects the temperature at the connection terminal (between the thermocouple and the instrument), and maintains it at the same status as if the reference junction location temperature were at  $0^{\circ}$ C ( $32^{\circ}$ F).

#### [Burnout]

When the thermocouple or RTD input is burnt out, OUT is turned OFF (for direct current output, OUT low limit value), and the PV Display flashes "".

[Input error indication]							
Output			Output status				
status	Contents		Cont	roller/Co	nverter		
when input	and		Controller			Converter	
errors occur	Indication	0	UT1	OUT2		OL	JT1
(*1)		Direct action	Reverse action	Direct	Reverse	Direct	Reverse
07 0F.F.:	"----" flashes.	ON (20 mA) or OUT1 high limit value (*2) OFF (4 mA) or OUT1 low limit value	OFF (4 mA) or OUT1 low limit value	OUT2 low limit	value	20 mA or OUT1 high limit value	4 mA or OUT1 low limit value
07 0F.F.[]	"" flashes.	OFF (4 mA) or OUT1 low limit value	ON (20 mA) or OUT1 high limit value (*2) OFF(4 mA) or OUT1 low limit value	OUT2 low limit	value	4 mA or OUT1 low limit value	20 mA or OUT1 high limit value

- (\*1) [Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output. If OUT is not Direct current output, the output status will be the same as when  $\alpha FF$  is selected in [Output status when input errors] occur]. For manual control, the preset MV is output.
- (\*2) Outputs a value between OFF (4 mA) and ON (20 mA) or between OUT1 low limit value and OUT1 high limit value, depending on deviation.

Input	Input range	Indication range	Control range
КТ	–199.9 to 400.0℃	–199.9 to 450.0℃	<b>–205.0 to 450.0</b> ℃
К, Т	–199.9 to 750.0°F	–199.9 to 850.0°F	–209.0 to 850.0°F
	–199.9 to 850.0℃	–199.9 to 900.0℃	–210.0 to 900.0℃
Pt100	<b>–200 to 850</b> ℃	<b>–210 to 900</b> ℃	<b>−210 to 900</b> °C
PLIUU	<b>−199.9 to 999.9</b> °F	<b>–199.9 to 999.9</b> °F	<b>–211.0 to 1099.9</b> °F
	<b>–300 to 1500</b> °F	<b>–318 to 1600</b> °F	<b>–318 to 1600</b> °F
	–199.9 to 500.0℃	–199.9 to 550.0℃	<b>–206.0 to 550.0</b> ℃
JPt100	<b>–200 to 500</b> ℃	<b>–207 to 550</b> ℃	<b>–207 to 550</b> ℃
	–199.9 to 900.0°F	<b>–199.9 to 999.9</b> °F	<b>–211.0 to 999.9</b> °F
	<b>–300 to 900</b> °F	<b>–312 to 1000</b> °F	<b>–312 to 1000</b> °F

#### Thermocouple, RTD input

Indication range and Control range for thermocouple inputs except above:

[Input range low limit value  $-50^{\circ}$ C (100<sup>°</sup>F)] to [Input range high limit value  $+50^{\circ}$ C (100<sup>°</sup>F)]

#### **DC** input

Indication range: [Scaling low limit value – Scaling span x 1%] to [Scaling high limit value + Scaling span x 10%]

> However, if the input value is out of the range -1999 to 9999, the PV Display flashes " or " - - - ".

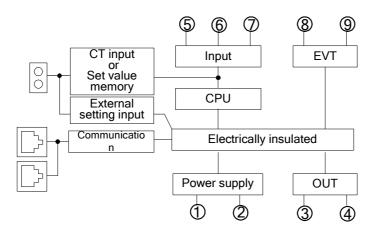
Control range: [Scaling low limit value – Scaling span x 1%] to [Scaling high limit value + Scaling span x 10%]

#### DC input disconnection

When DC input is burnt out, the PV Display flashes "\_\_\_\_" for 1 to 5 V DC and 4 to 20 mA DC inputs, and " for 0 to 1 V DC input.

For 0 to 5 V DC, 0 to 10 V DC and 0 to 20 mA DC inputs, the PV Display indicates the value corresponding with 0 V or 0 mA input.

#### Insulation/Dielectric strength: Circuit insulation configuration



Insulation resistance: 10 M $\Omega\,$  min. at 500 V DC

Dielectric strength: 1.5 kV AC for 1 minute

Power supply: 100 to 240 V AC 50/60 Hz, 24 V AC/DC 50/60 Hz

Allowable voltage fluctuation range: 100 to 240 V AC: 85 to 264 V AC, 24 V AC/DC: 20 to 28 V AC

Power consumption: 100 to 240 V AC: Approx. 5 VA max. 24 V AC: Approx. 4 VA max.

24 V DC: Approx. 4 W max.

Ambient temperature: 0 to  $50^{\circ}$  (32 to  $122^{\circ}$ F)

Ambient humidity:	35 to 85%RH (non-condensing)
Weight:	Approx.100 g
External dimension:	22.5 x 75 x 100 mm (W x H x D)
Material:	Flame-resistant resin (Case)
Color:	Light gray (Case)

#### Accessories included:

Instruction manual excerpt: 1 copy

When Heater burnout alarm output (W option) is ordered: Connector harness W 3 m: 1 length When Heater burnout alarm output (W option) is ordered:

For rated current 5A, 10A, 20A: CT (CTL-6S): 1 piece

For rated current 50A: CT (CTL-12-S36-10L1U): 1 piece

When Set value memory external selection (EI option) is ordered:

Connector harness AOJ 3 m: 1 length

When External setting input (EA option) is ordered: Connector harness AOJ 3 m: 1 length

Accessories sold separately: 50  $\Omega$  shunt resistor for direct current input

#### **10.2 Optional Specifications**

#### Heater burnout alarm output (W option)

Watches the heater current with CT (Current transformer), and detects the burnout. This alarm is also activated when sensor is burnt out, or when indication is overscale or underscale. Heater burnout alarm, Alarm and Loop break alarm utilize common output terminals. This option cannot be used for direct current output type. Rating: 5 A [W (5 A)], 10 A [W (10 A)], 20 A [W (20 A)], 50 A [W (50 A)] (Must be specified)

Setting range: 5 A [W (5 A)]: 0.0 to 5.0 A (OFF when set to 0.0) 10 A [W (10 A)]: 0.0 to 10.0 A (OFF when set to 0.0)

20 A [W (20 A)]: 0.0 to 20.0 A (OFF when set to 0.0)

50 A [W (50 A)]: 0.0 to 50.0 A (OFF when set to 0.0)

Setting accuracy:  $\pm 5\%$  of the heater rated current

Action point: Setting value

Action: ON/OFF action

Output: Open collector, Control capacity: 0.1 A 24 V DC

#### Serial communication (C5 option)

The following operations are performed from an external computer.

(1) Reading and writing of the SV, PID and other various set values

(2) Reading of the PV and action status

(3) Function change

Cable length : Max. 1.2 km, Cable resistance: Within 50  $\Omega$  (Terminators are not necessary, but

if used, use 120  $\Omega$  or more on one side.)

Communication line:	EIA RS-485
Communication method:	Half-duplex communication
Communication speed:	2400/4800/9600/19200/38400 bps (Default: 9600bps)(Selectable by keypad)
Synchronization method:	Start-stop synchronization
Data bit/Parity:	7, 8/Even, Odd, No parity (Selectable by keypad)
Stop bit:	1, 2 (Selectable by keypad)
Communication protocol	: Shinko protocol/Modbus ASCII/Modbus RTU (Selectable by keypad)
	(Default: Shinko protocol)

Data format:

Communication protocol	Shinko protocol	Modbus ASCII	Modbus RTU
Start bit	1	1	1
Data bit	7	7	8
Parity	Even	Even (Odd, No parity)	No parity (Even, Odd)
Stop bit	1	1 or 2	1 or 2

Error correction: Command request repeat system

Error detection: Parity check, checksum (Shinko protocol), LRC (Modbus ASCII), CRC-16 (Modbus RTU) Digital external setting:

SV of the programmable controller (with the SVTC option) can be digitally transmitted to the DCL-33A (with the C5 option) by combining the programmable controller with the DCL-33A. When data from the programmable controller is larger than SV high limit or smaller than SV low limit, DCL-33A ignores the value and controls with the previous value. The control desired value adds SVTC bias value to the value received by the SVTC command.

#### Heating/Cooling control output (DC option)

OUT2 proportional band: 0.0 to 10.0 times OUT1 proportional band (ON/OFF control when set to 0.0) Integral time: Same as that of OUT1

Derivative time: Same as that of OUT1

OUT2 proportional cycle: 1 to 120 seconds

Overlap/Dead band: Thermocouple, RTD input: −100.0 to 100.0°C (°F)

DC voltage, current input: –1000 to 1000 (The placement of the decimal point follows the selection)

OUT2 ON/OFF hysteresis: Thermocouple, RTD input: 0.1 to 100.0℃ (°F)

DC voltage, current input: 1 to 1000 (The placement of the decimal point follows the selection.)

OUT2 high limit, OUT2 low limit: 0 to 100%

OUT2 cooling mode: Air cooling (Linear characteristics), Oil cooling (1.5th power of the linear characteristics), Water cooling (2nd power of the linear characteristics)

Output: Open collector, control capacity: 0.1 A 24 V DC

#### Set value memory external selection (El option)

Switches SV1 and SV2 by external contact. If 001 is selected in [Event input DI allocation]: DI input Open: SV1 DI input Closed: SV2 If 008 is selected in [Event input DI allocation]: DI input Open: SV2 DI input Closed: SV1 Circuit current when closed: Approx. 2 mA

#### External setting input (EA option)

If 'Remote' is selected in [Remote/Local], external analog signal will become SV.

Remote bias value is added to the control desired value.

Setting signal: Direct current 4 to 20 mA

Allowable input: 50 mA DC max.

Input impedance: 50  $\Omega$  max.

Input sampling period: 125 msec

<b>Option combination</b>	(•: Can be used together.)
---------------------------	----------------------------

1		<u> </u>	,		
Option Code	W	DC	C5	EA	EI
W	/	•	•	-	-
DC	•		•		•
C5					
EA	-	•	•	/	-
EI	-	•	•	-	

W, EA and EI options cannot be used together.

**11. Troubleshooting** If any malfunctions occur, refer to the following after checking that power is being supplied to the controller. **11.1 Indication** 

•

Problem	Possible Cause	Solution
[ ] is flashing on the PV Display.	Burnout of thermocouple, RTD or disconnection of DC voltage (0 to 1 V DC)	Replace each sensor. How to check whether the sensor is burnt out [Thermocouple] If the input terminals of the instrument are shorted, and if a value around room temperature is indicated, the instrument is likely to be operating normally, however, the sensor may be burnt out. [RTD] If approx. 100 $\Omega$ resistance is connected to the input terminals between A-B of the instrument and between B-B is shorted, and if a value around 0°C (32°F) is indicated, the instrument is likely to be operating normally, however, the sensor may be burnt out. [DC voltage (0 to 1 V DC)] If the input terminals of the instrument are shorted, and if a scaling low limit value is indicated, the instrument is likely to be operating normally, however, the signal wire may be disconnected. Connect the sensor terminals to the instrument terminals securely.
[] is flashing on the PV Display.	Mounted to the instrument input terminals. The input signal wire for DC voltage (1 to 5 V DC) or direct current (4 to 20 mA DC) may be disconnected. Check whether the input signal wire for DC voltage (1 to 5 V DC) or	How to check whether the input signal wire is disconnected [DC voltage (1 to 5 V DC)] If the input to the input terminals of this controller is 1 V DC, and if a value corresponding to 1 V DC is indicated, the controller is likely to be operating normally, however, the signal wire may be disconnected. [Direct current (4 to 20 mA DC)] If the input to the input terminals of this controller is 4 mA DC, and if a value corresponding to 4 mA DC is indicated, the controller is likely to be operating normally, however, the signal wire may be disconnected. Connect the signal wire to the controller input terminals securely.
	Direct current (4 to 20 mA DC) is securely connected to the controller input terminals. Check whether the polarity of thermocouple or compensating lead wire is correct. Check whether codes (A, B, B) of the RTD match with the controller input terminals	Wire them correctly.

Problem	Possible Cause	Solution
The value set in	Check whether the input signal wire	How to check whether the input
[Scaling low limit]	for DC voltage (0 to 5 V DC, 0 to 10	signal wire is disconnected
remains on the PV	V DC) or direct current (0 to 20 mA	[DC voltage (0 to 5 V DC, 0 to 10 V
Display.	DC) is disconnected.	DC)]
		If the input to the input terminal of
		this controller is 1 V DC, and if a
		value (converted value from Scaling
		high, low limit setting) corre-
		sponding to 1 V DC is indicated, the
		controller is likely to be operating
		normally, however, the signal wire
		may be disconnected.
		[Direct current (0 to 20 mA DC)]
		If the input to the input terminal of this controller is 4 mA DC, and if
		a value (converted value from
		Scaling high, low limit setting) corre-
		sponding to 4 mA DC is indicated,
		the controller is likely to be
		operating normally, however, the
		signal wire may be disconnected.
	Check whether the input signal wire	Connect the signal wire to the
	for DC voltage (0 to 5 V DC, 0 to 10	controller input terminals securely.
	V DC) or direct current (0 to 20 mA	
	DC) is securely connected to the	
	controller input terminals.	
The indication of the	Check whether the sensor input or	Set the sensor input and the
PV Display is abnormal	temperature unit (°C, °F) is correct.	temperature unit (°C, °F) correctly.
or unstable.	Sensor correction value is not	Set it to a suitable value.
	suitable.	
	Check whether the sensor	Set the sensor specification properly.
	specification is correct.	
	AC leaks into the sensor circuit.	Use an ungrounded type sensor.
	There may be equipment that	Keep the instrument clear of any
	interferes with or makes noise near	potentially disruptive equipment.
	the instrument.	
[E i] is indicated on	The internal memory is defective.	Please contact our main office or
the PV Display.		dealers.

### 11.2 Key Operation

Problem	Possible Cause	Solution
• Settings (SV, P, I, D,	Set value lock (Lock 1 or Lock 2) is	Release the lock selection.
proportional cycle,	selected.	
alarm value, etc.) are impossible.	Auto-tuning (AT) is performing.	Cancel auto-tuning (AT) if required.
• The values do not		
change by the $\bigtriangleup$ or		
key.		
The setting indication	Scaling high limit or low limit (in	Set it to a suitable value while in
does not change within	Auxiliary function setting mode 2)	Auxiliary function setting mode 2.
the rated input range	may be set at the point where the	
even if the $\bigtriangleup$ or $\bigtriangledown$	value does not change.	
key is pressed, and new	C C	
values are unable to be		
set.		

### 11.3 Control

Problem	Possible Cause	Solution
The PV (temperature)	The sensor is out of order.	Replace the sensor.
does not rise.	Check whether the sensor is	Mount the sensor or control output
	securely mounted to the instrument	terminals securely.
	input terminals, or control output	
	terminals are securely mounted	
	to the actuator input terminals.	
	Ensure that wiring of sensor	Wire them correctly.
	terminals or control output terminals	
	is correct.	
The control output	OUT low limit value is set to 100%	Set it to a suitable value.
remains in an ON	or higher in Auxiliary function	
status.	setting mode 2.	
The control output	OUT high limit value is set to 0% or	Set it to a suitable value.
remains in an OFF	less in Auxiliary function setting	
status.	mode 2.	

For all other malfunctions, please contact our main office or dealers.

# **12. Character Table**

## 12.1 Main Setting Mode

Character	Setting Item, Description, Setting Range	Factory Default
<b>۲</b>	SV1	<b>0</b> °C
	Scaling low limit to scaling high limit (For DC voltage, current input,	
	the placement of the decimal point follows the selection.)	

#### 12.2 Sub Setting Mode

Character	Setting Item, Description, Setting Ran	ge	Factory Default
Ar	AT Perform/Cancel		AT Cancel
	: AT Cancel		
	RF AT Perform		
P	OUT1 proportional band		2.5%
	0.0 to 110.0%		
Р_Ь	OUT2 proportional band		1.0 times
	0.0 to 10.0 times		
1	Integral time		200 sec
	0 to 3600 sec		
d	Derivative time		50 sec
	0 to 1800 sec		
<i>П</i>	ARW (Anti-reset windup)		50%
	0 to 100%		
	OUT1 proportional cycle	Relay contact output: 30 sec	
	1 to 120 sec Non-contact vo		Itage output: 3 sec
c _ b []	OUT2 proportional cycle		3 sec
	1 to 120 sec		
- 4EF	Manual reset		0.0
	±Proportional band converted value (For DC voltag		
8 (	the placement of the decimal point follows the selection.)		0.0
			0°C
	See (Table 12.2-1)(p.48). (For DC voltage, current in	•	
H	placement of the decimal point follows the selection. Heater burnout alarm value	)	0.0 A
XX.X	Rated current 5 A: 0.0 to 5.0 A		0.0 A
alternating	Rated current 10 A: 0.0 to 10.0 A		
display	Rated current 20 A: 0.0 to 20.0 A		
uispiay	Rated current 50 A: 0.0 to 50.0 A		
1.7_5	Loop break alarm time		0 minutes
	0 to 200 minutes		
LP_H	Loop break alarm span		0°C
	Thermocouple, RTD input: 0 to 150°C (°F) or 0.0 to 1	50.0°C (°F)	
	DC voltage, current input: 0 to 1500 (The placement	• •	
	point follows the selection		
L	P	1	1

### (Table 12.2-1)

Alarm Type	Setting Range	
High limit alarm	–(Scaling span) to scaling span	Minimum
Low limit alarm	–(Scaling span) to scaling span	negative value:
High/Low limits alarm	0 to scaling span	-199.9 or -1999
High/Low limit range alarm	0 to scaling span	
Process high alarm	Scaling low limit value to scaling high limit value	Maximum
Process low alarm	Scaling low limit value to scaling high limit value	positive value:
High limit with standby alarm	–(Scaling span) to scaling span	999.9 or 9999
Low limit with standby alarm	–(Scaling span) to scaling span	
High/Low limits with standby alarm	0 to scaling span	
High/Low limits independent alarm	0 to scaling span	
High/Low limit range independent	0 to scaling span	
alarm		
High/Low limits with standby	0 to scaling span	
independent alarm		

## 12.3 Auxiliary Function Setting Mode 1

Character	Setting Item, Setting Range	Factory Default
Lock	Set value lock	Unlock
	(Unlock): All set values can be changed.	
	$L \Box \subset \frac{1}{2}$ (Lock 1): None of the set values can be changed.	
	$\frac{1}{2} \Box \Box \Box \overline{c}'$ (Lock 2): Only main setting mode can be changed.	
	$L \Box \subset \exists$ (Lock 3): All set values – except [input type] and [Controlle	
	be changed. However, changed values revert to their previou power is turned off because they are not saved in the non-vo	
	Do not change any setting item in Auxiliary function setting m	•
	in Auxiliary function setting mode 2 is changed, it will affect o such as the SV and Alarm value.	•
	Be sure to select Lock 3 when changing the set value freque	ntly via software
	communication. (If a value set by the software communicatio	
	the value before the setting, the value will not be written in no	
<i>Ъ</i>	Sensor correction	0.0℃
	Thermocouple, RTD input: –100.0 to 100.0℃(℉)	
	DC voltage, current input: -1000 to 1000 (The placement of the	
-,,	decimal point follows the selection.)	
<i>ธ</i> กีรใ	Communication protocol	Shinko protocol
	กตก็L : Shinko protocol กัดสี่ที่: Modbus ASCII mode	
	توقط: Modbus ASCII mode قوظة: Modbus RTU mode	
	book : Shinko protocol (Block read available)	
	$b \overline{a} d \overline{B}$ : Modbus ASCII mode (Block read available)	
	ಓಗದ್: Modbus RTU mode (Block read available)	
cñna	Instrument number	0
	0 to 95	
575P	Communication speed	9600 bps
	[]] 낙원: 4800 bps	
	□□ <i>□□□□□□</i> □□□□□□□□□□□□□□□□□□□□□□□□□□□□	
	192: 19200 bps	
	<i>∃∃∃</i> Ч: 38400 bps	
cñPr	Parity	Even
	οφοΕ: No parity ΕΒΕο: Even	
	add Odd	
<u>ะกั</u> รโ	Stop bit	1
	1 or 2	

### 12.4 Auxiliary Function Setting Mode 2

Character	Setting	g Item, Setting Rai	nge	Factory Default
48-9-2	Input type			K(-200 to 1370℃)
	<u>-20</u>	00 to 1370℃	£	-320 to 2500°F
	<i>E</i> □. <i>E</i> : -19	99.9 to 400.0℃	E□ .F:	-199.9 to 750.0°F
		00 to 1000℃	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	-320 to 1800°F
	<i>-</i>	<b>:o 1760</b> ℃		0 to 3200°F
		o 1760℃		0 to 3200°F
		to 1820℃		0 to 3300°F
		00 to 800℃		-320 to 1500°F
		99.9 to 400.0℃		-199.9 to 750.0°F
		00 to 1300℃		-320 to 2300°F
		to 1390℃		0 to 2500°F
	<i>c</i> □□ <i>C</i> : C(W/Re5-26) 0 t		<i>c</i> □□ <i>F</i> : C(W/Re5-26)	
		99.9 to 850.0℃	' '	-199.9 to 999.9°F
		99.9 to 500.0℃		-199.9 to 900.0°F
		00 to 850℃		-300 to 1500°F
		00 to 500℃		-300 to 900°F
	<i>닉근입유</i> : 4 to 20 mA DC - '			
	<i>□⊇□用</i> : 0 to 20 mA DC -	•	mally mounted 50 $\Omega$ sh	unt resistor)
		1999 to 9999		
	$\Box \Box \Box \Xi H$ : 0 to 5 V DC -	1999 to 9999		
		1999 to 9999		
	<i>□                                    </i>	1999 to 9999		
	<i>닉귿딥</i> : : 4 to 20 mA DC - ·	1999 to 9999 (Built-	in 50 $\Omega$ shunt resistor)	
	<i>□2□</i> /::0 to 20 mA DC -:	1999 to 9999 (Built-	in 50 $\Omega$ shunt resistor)	
$5\Gamma LH$	Scaling high limit			<b>1370</b> ℃
	Scaling low limit to input	range high limit		
	(For DC voltage, current	input, the placemer	nt of the decimal point	
	follows the selection.)			
5766	Scaling low limit			<b>-200</b> ℃
	Input range low limit to so			
(For DC voltage, current input, the placement of the decimal point				
	follows the selection.)			
dP	Decimal point place			No decimal point
	$\Box \Box \Box \Box \Box$ : No decimal poin	nt		
	$\Box \Box \Box \Box$ : 1 digit after deci			
	$\Box \Box \Box \Box \Box$ : 2 digits after dec			
·	Image: Constraint of the second sec	cimal point		
FILF	PV filter time constant			0.0 sec
	0.0 to 10.0 sec			
ol H	OUT1 high limit			100%
	OUT1 low limit value to 1			
	(Direct current output typ	e: OUT1 low limit v	alue to 105%)	
oll 🗌	OUT1 low limit			0%
	0% to OUT1 high limit va			
	(Direct current output typ		gh limit value)	
HY50	OUT1 ON/OFF hysteresis			1.0°℃
	Thermocouple, RTD inpu			
	DC voltage, current input			
		point follows the s	election.)	
cAcT	OUT2 cooling mode			Air cooling
	$\exists i \in \Box$ : Air cooling			
	□/ L . Oil cooling			
	<i>こ号に</i> : Water cooling			

Character	Setting Item, Setting Range	Factory Default
ol Hb	OUT2 high limit	100%
	OUT2 low limit value to 100%	
ollb	OUT2 low limit	0%
	0% to OUT2 high limit value	
db	Overlap/Dead band	0.0°C
	Thermocouple, RTD input: –100.0 to 100.0°C (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	
	point follows the selection.)	
<i>НУЧЬ</i>	OUT2 ON/OFF hysteresis	1.0℃
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	
	point follows the selection)	
RL IF	Alarm 1 type	No alarm action
	: No alarm action	
	High limit alarm	
	L. Low limit alarm	
	HL III: High/Low limits alarm	
	ມ່ d⊡: High/Low limit range alarm	
	R'- Process high alarm	
	ー 月 ら	
	$H_{\rm m}$ High limit with standby alarm	
	Lunie Low limit with standby alarm	
	$H_{L}^{\prime}$ $\square \tilde{\mu}$ : High/Low limits with standby alarm	
	I HL : High/Low limits independent alarm	
	$i  \bar{\omega} i  d$ : High/Low limit range independent alarm	
	$I H L \bar{\omega}$ : High/Low limits with standby independent alarm	
RILA	Alarm 1 Energized/De-energized	Energized
	nonL: Energized	
	-EB-: De-energized	
R IHd	Alarm 1 HOLD function	Not holding
	$\sigma \sigma \sigma \mathcal{E}$ : Not holding	
	Holding	
8 189	Alarm 1 hysteresis	1.0℃
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the	
	decimal point follows the selection.)	
8 189	Alarm 1 delay time	0 sec
	0 to 9999 sec	
coní	Direct/Reverse action	Reverse
	HERIT: Reverse (Heating) action	(Heating) action
	$c \Box \Box L$ : Direct (Cooling) action	( C,
85_5	AT bias	<b>20</b> ℃
	0 to 50℃ (0 to 100°F), or 0.0 to 50.0℃ (0.0 to 100.0°F)	
58_5	SVTC bias	0
	$\pm 20\%$ of the scaling span	
Eaur	Output status when input errors occur	Output OFF
	$\Box F F \square$ : Output OFF: OFF(4mA) or OUT1 low limit value.	
	Doministic Output ON: Outputs a value between OFF (4mA) and ON	
	(20mA) or between OUT1 low limit value and OUT1 high	
	limit value, depending on deviation.	
Fline	Controller/Converter	Controller
	בחלה: Controller	
		1

### 12.5 Auxiliary Function Setting Mode 3

Character		Setting Item, S	etting Range		Factory Default	
El n	Event in	put DI allocation			No event	
		Event Input Function	Input ON (Closed)	Input OFF (Open)		
	000	No event				
	00 I	Set value memory	SV2	SV1		
	002	Control ON/OFF	Control OFF	Control ON		
	003	Direct/Reverse action	Direct	Reverse		
	004	Preset output 1 ON/OFF	Preset output	Usual control		
	005	Preset output 2 ON/OFF	Preset output	Usual control		
	005	Auto/Manual control	Manual	Automatic		
	ר ממ	Integral action Holding (Stop)/Usual integral action	Integral action Holding (Stop)	Usual integral action		
	008	Set value memory	SV1	SV2		
	009	Control ON/OFF	Control ON	Control OFF	1	
		Direct/Reverse action	Reverse	Direct	1	
		Preset output 1 ON/OFF	Usual control	Preset output		
	012	Preset output 2 ON/OFF	Usual control	Preset output		
	013	Auto/Manual control	Automatic	Manual		
	014	Integral action Holding	Usual integral	Integral action		
		(Stop)/Usual integral	action	Holding (Stop)		
		action			-	
	00 I 008					
72	SV2	<u> </u>			<b>0</b> ℃	
	Scaling	low limit to Scaling high lin	nit			
7 / 5 / 7	-	value 0 Enabled/Disabled			Disabled	
	9E 4□	: Enabled				
7 IH::	Alarm 1	high limit alarm value			0°C	
	See (Table 12.2-1) on p.48.					
	(For DC voltage and current input, the placement of the decimal					
	point fo	llows the selection)				
RL 2F	Alarm 2	••			No alarm action	
		: No alarm action				
	High limit alarm					
		Letter Low limit alarm				
	HL High/Low limits alarm					
	úi d⊡ High/Low limit range alarm					
	吊っ: Process high alarm 「吊っ…: Process low alarm					
	$H = \tilde{\omega}$ : High limit with standby alarm $L = \tilde{\omega}$ : Low limit with standby alarm					
	$HL \square \overline{\mu}$ : High/Low limits with standby alarm					
		High/Low limits independ	•			
		: High/Low limit range inde				
		: High/Low limits with stand		alarm		

Character	Setting Item, Setting Range Factory Default		
8238	Alarm 2 value 0 Enabled/Disabled	Disabled	
	ロロロー: Disabled ビビンー: Enabled		
82	Alarm 2 value	0°C	
	See (Table 12.2-1) on p.48. (For DC voltage, current input, the		
	placement of the decimal point follows the selection.)		
R2H	Alarm 2 high limit alarm value	<b>0</b> ℃	
	See (Table 12.2-1) on p.48. (For DC voltage, current input, the		
	placement of the decimal point follows the selection.)		
82LA	Alarm 2 Energized/De-energized	Energized	
	nonL: Energized		
	r E 岩 与: De-energized		
RSH9	Alarm 2 HOLD function	Not holding	
	הבהב: Not holding		
	Hal d: Holding		
8289	Alarm 2 hysteresis	1.0℃	
	Thermocouple, RTD input: 0.1 to 100.0°C (°F)		
	DC voltage, current input: 1 to 1000 (The placement of the decimal		
	point follows the selection.)		
8243	Alarm 2 delay time	0 sec	
	0 to 9999 sec		
RL 3F	Alarm 3 type	No alarm action	
	: No alarm action		
	High limit alarm		
	L Low limit alarm		
	H'L High/Low limits alarm		
	$\vec{\omega} \mid \vec{d}$ : High/Low limit range alarm		
	R'- Process high alarm		
	rB		
	H		
	L. Low limit with standby alarm		
	$H'_L \square \tilde{\omega}$ : High/Low limits with standby alarm		
	$i = \frac{1}{2} i = \frac{1}{2}$ High/Low limit range independent alarm		
	$H_{L}$ $\tilde{\omega}$ : High/Low limits with standby independent alarm		
8358	Alarm 3 value 0 Enabled/Disabled	Disabled	
83	Alarm 3 value	0°C	
	See (Table 12.2-1) on p.48. (For DC voltage, current input, the		
	placement of the decimal point follows the selection.)		
ЯЗН□	Alarm 3 high limit alarm value	<b>0</b> °C	
	See (Table 12.2-1) on p.48. (For DC voltage, current input, the		
	placement of the decimal point follows the selection.)		
RBLA	Alarm 3 Energized/De-energized	Energized	
	ngnL: Energized		
	ー <sup>E</sup> 台 <sup>-</sup> - : De-energized		

Character	Setting Item, Setting Range	Factory Default
АЗНА	Alarm 3 HOLD function	Not holding
	$aaa \xi$ : Not holding	
	Halding	
АЗНУ	Alarm 3 hysteresis	1.0°℃
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	
	point follows the selection.)	
8388	Alarm 3 delay time	0 sec
	0 to 9999 sec	0 000
RL 4F	Alarm 4 type	No alarm action
	: No alarm action	
	High limit alarm	
	High/Low limits alarm	
	$\vec{\omega} \neq \vec{\omega}$ High/Low limits alarm	
	A     A <td></td>	
	$r B = \Box$ : Process low alarm	
	H High limit with standby alarm	
	L Low limit with standby alarm	
	HL	
	<i>HL</i> High/Low limits independent alarm	
	$i  \vec{\omega}  \vec{i}$ : High/Low limit range independent alarm	
8418	<i>! HL u</i> : High/Low limits with standby independent alarm	
8728	Alarm 4 value 0 Enabled/Disabled	Disabled
<b>1</b>	<u> ソモッ</u> : Enabled	• 0 =:
84	Alarm 4 value	0°C
	See (Table 12.2-1) on p.48. (For DC voltage, current input, the	
	placement of the decimal point follows the selection.)	
ЯЧН□	Alarm 4 high limit alarm value	<b>0</b> °C
	See (Table 12.2-1) on p.48. (For DC voltage, current input, the	
	placement of the decimal point follows the selection.)	
84LA	Alarm 4 Energized/De-energized	Energized
	nañt : Energized	
	r E 岩 っ: De-energized	
ЯЧНЫ	Alarm 4 HOLD function	Not holding
	הבה <sup>ב</sup> : Not holding	
	HoLd: Holding	
ЯЧНУ	Alarm 4 hysteresis	1.0℃
	Thermocouple, RTD input: 0.1 to 100.0℃ (°F)	
	DC voltage, current input: 1 to 1000 (The placement of the decimal	
	point follows the selection.)	
8489	Alarm 4 delay time	0 sec
	0 to 9999 sec	
-87	Remote/Local	Local
	$r E \overline{\rho} \overline{\Gamma}$ : Remote	
-5-5	Remote bias	0°C
· · • •	$\pm 20\%$ of input span	
		1

Character	Setting Item, Setting Range	Factory Default
FFLH	External setting input high limit	<b>1370</b> ℃
	External setting input low limit to Scaling high limit	
$-\Gamma L L$	External setting input low limit	<b>−200</b> °C
	Scaling low limit to External setting input high limit	
- <i>8</i> 55	SV Rise/Fall rate start type	SV start
	らどうだ : SV start	
	PBらF: PV start	
- 8F U	SV rise rate	0 °C/minute
	0 to 9999 °C/min (°F/min) (The placement of the decimal point	
	follows the selection.)	
	Thermocouple, RTD input: 0.0 to 999.9 °C/min (°F/min)	
	DC voltage, current input: 0 to 9999/min	
-AFd	SV fall rate	0 °C/minute
	0 to 9999 $^\circ$ C/min ( $^\circ$ F/min) (The placement of the decimal point	
	follows the selection.)	
	Thermocouple, RTD input: 0.0 to 999.9 °C/min (°F/min)	
	DC voltage, current input: 0 to 9999/min	
PoUF	Control output OUT1/EVT	OUT1
	<i>교님티 I</i> : OUT1	
Hahl	Heater burnout alarm output Enabled/Disabled	Enabled
	n 🕫 🗔 Elisabled	
	<i>님돈</i> 누□: Enabled	
LP4L	Loop break alarm output Enabled/Disabled	Enabled
	n p Disabled	
	성문 노 Enabled	
A 14L	Alarm 1 output Enabled/Disabled	Enabled
	성도 가드: Enabled	
8241	Alarm 2 output Enabled/Disabled	Disabled
	성은 누⊡: Enabled	
8341	Alarm 3 output Enabled/Disabled	Disabled
	Service Enabled	Dischlad
8441	Alarm 4 output Enabled/Disabled	Disabled
	ソE つ Enabled	
P45 (	OUT1 MV Preset value	0.0%
	OUT1 low limit to OUT1 high limit	
P472	OUT2 MV Preset value	0.0%
	OUT2 low limit to OUT2 high limit	
ā8nU	SUB-MODE key function	Control output
	$\Box FF \square$ : Control output OFF	OFF
	<u>ดีสิตป</u> : Auto/Manual control	
	RL oF: Alarm HOLD cancel	
	Auto/Manual control after power ON	Automatic
	RUF a: Automatic control	control
1	- <sup>デ</sup> パーム: Manual control	

## **Key Operation Flowchart**

#### Basic Operation Procedure

PV/SV Display

[Main setting mode]

PV **5** SV1

Set the input type, Alarm 1 type and SV1 (desired value), following the procedure below. Setting item numbers (1), (2), (3), (4), (5), (6), (7) and (8) are indicated on the flowchart.

[Step 1]	Turn the load circuit power OFF, and turn the power to the
Operation before RUN	DCL-33A ON.
	<ul><li>Select an input type and Alarm 1 type, etc. in Auxiliary function setting mode 2.</li><li>(1) Select an input type in [Input type].</li><li>(2) Select the Alarm 1 type in [Alarm 1 type].</li></ul>
[Step 2] Auxiliary function setting mode 2	<ul> <li>If any Alarm 1 type except () is selected, (3) to (6) will be indicated. Set them if necessary.</li> <li>Note: If Alarm 1 type is changed, the Alarm 1 value will default to 0 (0.0). Therefore, set the alarm value again.</li> <li>(3) Select Alarm 1 Energized/De-energized in [Alarm 1 Energized/De-energized].</li> <li>(4) Select either Alarm 1 Holding or Not holding in [Alarm 1 HOLD function].</li> <li>(5) Set the Alarm 1 hysteresis in [Alarm 1 hysteresis].</li> <li>(6) Set the Alarm 1 delay time in [Alarm 1 delay time].</li> </ul>
[Step 3] Sub setting mode	(7) Set the Alarm 1 value in [Alarm 1 value].
[Step 4] Main setting mode	(8) Set the SV1 (desired value) in [SV1 (desired value)].
[Step 5] RUN	Turn the load circuit power ON. Control action starts so as to keep the control target at the SV1 (desired value).

PV/SV Display

Output MV (manipulated

variable) indication

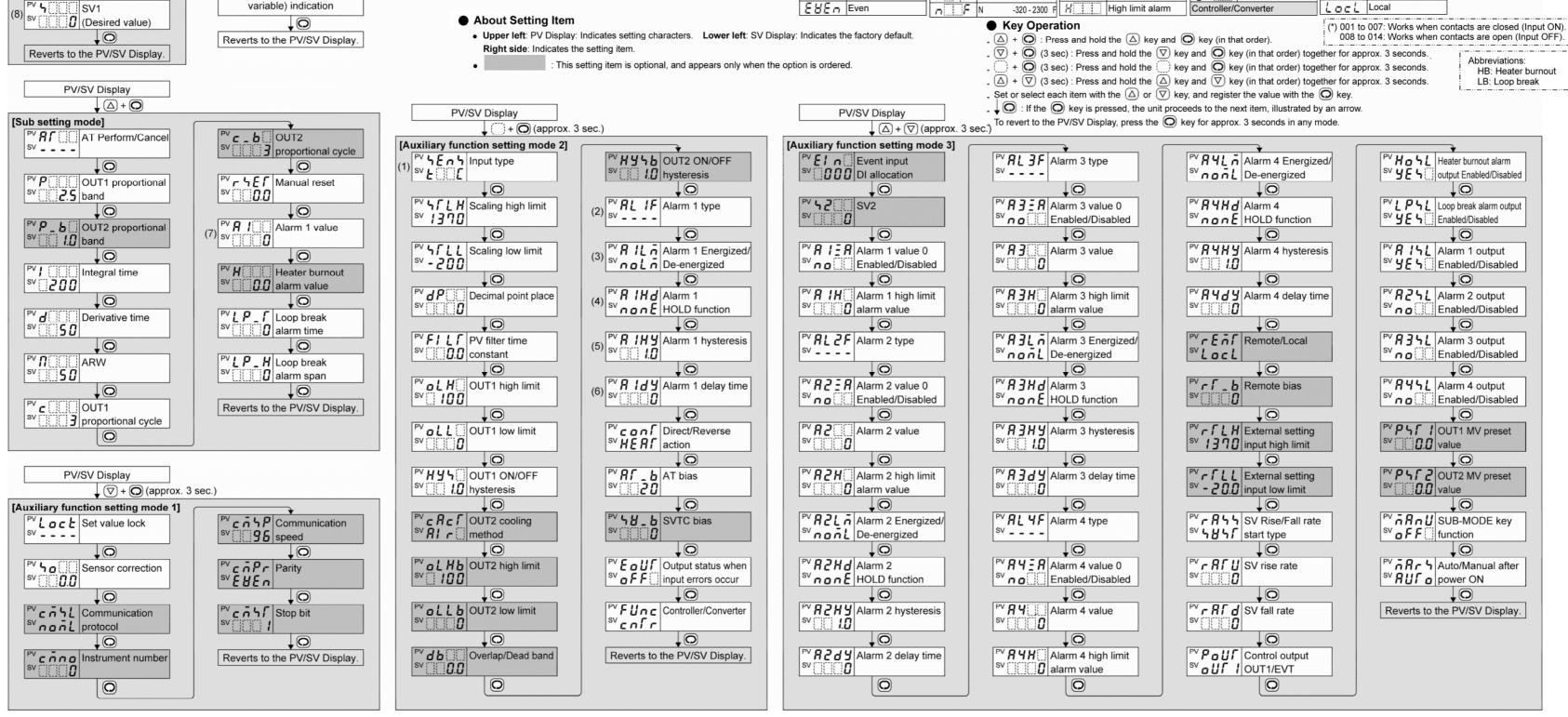
(approx. 3 sec.)

#### The alarm action is $\pm$ deviation setting from the SV. The alarm is activated if the input value reaches the High limit alarm high limit set value The alarm action is $\pm$ deviation setting from the SV. Low limit alarm The alarm is activated if the input value goes under the low limit set value. Combines High limit and Low limit alarm actions. When input value reaches the high limit set value or goes under the low limit set value, the alarm is High/Low limits alarm activated. When input value is between the high limit and low High/Low limit range limit set values, the alarm is activated. alarm Within the scale range of the controller, alarm action points can be set at random and if the input reaches Process alarm the randomly set action point, the alarm is activated. After the power supply to the instrument is turned on, even if the input enters the alarm action range, High limit alarm with standby Low limit alarm with the alarm is not activated. If SV is changed while the controller is running, the alarm is not activated standby even if the input is in the alarm action range. (If the controller is allowed to keep running, the standby function will be released once the input exceeds the High/Low limits alarm with standby alarm action point.)

AT Perform/Cancel	odd Odd	PL2F PL-0 - 2500 F	Low limit alarm	Controller	-E-F Remote
Cancel	Input Type	C(W/Re5-26) 0 - 4200 F	H/L limits alarm	Converter	SV Rise/Fall rate start type
Perform	Е К -200-1370 С	PT F Pt100 -199.9 - 999.9 F	H/L limit range	Event input DI allocation (*)	승풍수는 SV start
Set value lock	μ. Ε K -199.9 - 400.0 C	JPT F JPt100 -199.9 - 900.0 F	Process high alarm	No event	PHS PV start
Unlock	J -200 - 1000 C		- 8 - Process low alarm	Set value memory	Control output OUT1/EVT
Loc / Lock 1	R 0-1760 C	JFTF JPt100 -300-900 F	High limit with standby	Control ON/OFF	/_ / OUT1
LOCZ Lock 2	5 S 0-1760 C	4208 4-20 mA -1999-9999	Low limit with standby	Direct/Reverse action	E BIT EVT
Loc 3 Lock 3	<u>Б</u> В 0-1820 С	0208 0-20 mA -1999-9999	H/L limits with standby	ON/OFF	HB alarm output Enabled/Disable
Communication protocol	E	0 18 0-1V -1999-9999	I HI H/L limits independent		Disabled
Shinko protocol	Г. <u>Г</u> Т -199.9 - 400.0 С	058 0-5V -1999-9999	, -, , H/L limit range	ON/OFF	SES Enabled
Code Modbus ASCII mode	-200 - 1300 C	158 1-5V -1999-9999	independent alarm	Auto/Manual control	LB alarm output Enabled/Disable
Shinko protocol	- PL2E PL-0 - 1390 (	0-10H 0-10V -1999-9999	H/L limits with standby	Integral action Holding	Disabled
Block read)	C(W/Re5-26) 0 - 2315 0		H/L limits with standby independent alarm	Set value memory	SES Enabled
Medbus ASCII med	PT _ Pt100 -199.9 - 850.0 C	0-20 mA -1999-9999	A1 - A4 Energized/De-energized	Control ON/OFF	A1 - A4 output Enabled/Disable
Block read)	JP100 -199.9 - 500.0 C	Decimal point place	noni Energized	Direct/Reverse action	Disabled
Modbus RTU mode	Pf Pt100 -200 - 850 C	No decimal point	-EH- De-energized		SES Enabled
Bindr (Block read)		1 digit after point	A1 - A4 HOLD function	ON/OFF	SUB-MODE key function
Communication speed	E F K -320-2500 F	2 digits after point	הקה E Not holding	Preset output 2	Carl I have
2400 bps	<u>Е</u> К -199.9 - 750.0 F	3 digits after point	Holding		<u> ネタッけ</u> Auto/Manual cont <i>吊しゅ</i> F Alarm HOLD can
닉 <i>팀</i> 4800 bps	F J -320 - 1800 F	OUT2 cooling method	Direct/Reverse action	Auto/Manual control	Auto/Manual after power O
95 9600 bps	F R 0-3200 F	Air cooling	HER Reverse action	Integral action Holding	
192 19200 bps	5 F S 0-3200 F	Oil cooling	cool Direct action	A1 - A4 value 0 Enabled/Disabled	
38400 bps	<u>Б</u> F В 0-3300 F	URIT Water cooling	Output status when input errors occur	Disabled	· 규유규님 Manual control
Parity	E -320 - 1500 F	A1 - A4 type	Dutput OFF	SE Enabled	
non E No parity	/	No alarm action	Output ON	Remote/Local	
EBEn Even	F N -320-2300 F	High limit alarm	Controller/Converter	Loci Local	

### About Setting Item

Alarm Type



## SHINKO TECHNOS CO., LTD. OVERSEAS DIVISION

Head Office URL: E-mail:

Head Office: 2-5-1, Senbahigashi, Minoo, Osaka, Japan

http://www.shinko-technos.co.jp/e/ overseas@shinko-technos.co.jp Tel: +81-72-727-6100 Fax: +81-72-727-7006

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